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Product Manual 36543 (Revision C, 02/2024) Original Instructions



DPG-210X Digital Controller

Programmable Controller for Isochronous Generators

Installation and Operation Manual



General

Read this entire manual and all other publications pertaining to the work to be performed before installing, operating, or servicing this equipment.

Practice all plant and safety instructions and precautions.

Precautions Failure to follow instructions can cause personal injury and/or property damage.



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Revisions

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If your publication is not there, please contact your customer service representative to get the latest copy.



Any unauthorized modifications to or use of this equipment outside its specified mechanical, electrical, or other operating limits may cause personal injury and/or property damage, including damage to the equipment. Any such unauthorized modifications: (i) constitute "misuse" and/or "negligence" within the meaning of the product warranty thereby excluding warranty coverage for any resulting damage, and (ii) invalidate product certifications or listings.



Revisions— A bold, black line alongside the text identifies changes in this publication since the last revision.

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Warnings and Notices

Important Definitions



This is the safety alert symbol used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.

- **DANGER** Indicates a hazardous situation, which if not avoided, will result in death or serious injury.
- **WARNING** Indicates a hazardous situation, which if not avoided, could result in death or serious injury.
- CAUTION Indicates a hazardous situation, which if not avoided, could result in minor or moderate injury.
- NOTICE Indicates a hazard that could result in property damage only (including damage to the control).
- **IMPORTANT** Designates an operating tip or maintenance suggestion.



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Automotive Applications	On- and Off-highway Mobile Applications: Unless Woodward's control functions as the supervisory control, customer should install a system totally independent of the prime mover control system that monitors for supervisory control of engine (and takes appropriate action if supervisory control is lost) to protect against loss of engine control with possible personal injury, loss of life, or property damage.
·	
IOLOCK	 IOLOCK: driving I/O into a known state condition. When a control fails to have all the conditions for normal operation, watchdog logic drives it into an IOLOCK condition where all output circuits and signals will default to their de-energized state as described below. <i>The system MUST be applied such that IOLOCK and power OFF states will result in a SAFE condition of the controlled device.</i> Microprocessor failures will send the module into an IOLOCK state. Discrete outputs / relay drivers will be non-active and de-energized. Analog and actuator outputs will be non-active and de-energized with zero voltage or zero current. Network connections like CAN stay active during IOLOCK. This is up to the application to drive actuators controlled over network into a safe state.
	 The IOLOCK state is asserted under various conditions, including: Watchdog detected failures Microprocessor failure PowerLin and PowerDown conditions
	 System reset and hardware/software initialization PC tool initiated
	NOTE—Additional watchdog details and any exceptions to these failure states are specified in the related section of the product manual.

NOTICE

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To prevent damage to a control system that uses an alternator or battery-charging device, make sure the charging device is turned off before disconnecting the battery from the system.

Battery Charging Device

Electrostatic Discharge Awareness

NOTICE	Electronic controls contain static-sensitive parts. Observe the following precautions to prevent damage to these parts:				
Electrostatic Precautions	 Discharge body static before handling the control (with power to the control turned off, contact a grounded surface and maintain contact while handling the control). Avoid all plastic, vinyl, and Styrofoam (except antistatic versions) around printed circuit boards. Do not touch the components or conductors on a printed circuit board with your hands or with conductive devices. To prevent damage to electronic components caused by improper handling, read and observe the precautions in Woodward manual 82715, Guide for Handling and Protection of Electronic Controls, Printed Circuit Boards, and Modules. 				

Follow these precautions when working with or near the control.

- 1. Avoid the build-up of static electricity on your body by not wearing clothing made of synthetic materials. Wear cotton or cotton-blend materials as much as possible because these do not store static electric charges as much as synthetics.
- Touch your finger to a grounded surface to discharge any potential before touching the control, smart valve, or valve driver, or installing cabling connectors. Alternatively, ESD mitigation may be used as well: ESD smocks, ankle or wrist straps and discharging to a reference grounds surface like chassis or earth are examples of ESD mitigation.
 - ESD build up can be substantial in some environments: the unit has been designed for immunity deemed to be satisfactory for most environments. ESD levels are extremely variable and, in some situations, may exceed the level of robustness designed into the control. Follow all ESD precautions when handling the unit or any electronics.
 - I/O pins within connectors have had ESD testing to a significant level of immunity to ESD, however do not touch these pins if it can be avoided.
 - Discharge yourself after picking up the cable harness before installing it as a precaution.
 - The unit is capable of not being damaged or improper operation when installed to a level of ESD immunity for most installation as described in the EMC specifications. Mitigation is needed beyond these specification levels.

IMPORTANT

External wiring connections for reverse-acting controls are identical to those for direct-acting controls.

Regulatory Compliance

EMC Limitations

Cabling

All cabling for this unit is limited to less than 30m (98.4'). See wiring diagrams for specific cable types required.

Power cabling is limited to less than 10m (32.8') in total length from its source; power is intended to be from a local bus structure. The control is NOT intended to have a power bus that is derived from a plant-wide distribution system, remote source, or similar "mains" type distribution systems. The power to the control should also be a dedicated circuit, directly to the battery or source via a power and return wire that are routed together.

See Manual 36526 for additional regulatory information, limitations, and wiring diagrams with specific, required cable types.

Power Bus

The power bus is intended to be a local bus without power line surges and to have inductive load kickback events suppressed. Therefore, the control's power input is not designed to withstand a charging system load dump, heavy inductive kickbacks, or heavy surge type pulses. If the control is installed outside its intended usage, as described in this manual, centralized voltage pulse suppression should be implemented to help protect the control and other components on the bus. (See Chapter 6: Installation Instructions.)

COMM Port

The COMM port is intended to be a service port, with only temporary connection during service or initial configuration. The COMM port is susceptible to some EMC phenomena and possible unintentional battery return currents.

- Battery return (B-) is also the communication signal common; typically, PCs connect the communication signal's common to protective earth. The PC grounding can provide an unintended return path for B- currents. If B- and the PC are grounded to protective earth, a communication isolator should be used between the PC and the control. Damage to the PC or control, and/or unintended operation may result from a broken battery return wire or the parallel path.
- 2. The pins inside the COMM port plug are susceptible to damage by ESD discharges, static electricity arcs. Care should be taken not to touch them with tools or put fingers into the port. Always touch your hand or tool to a grounded piece of metal (discharge ESD) prior to coming in contact with the communication port.
- 3. The input is susceptible to RF noise such as switching transients and transmitter signals coupled into the communication cable. Cable orientation and short cable length may be used to eliminate these issues, depending on the severity of the environment.

Chapter 1. General Information

Introduction

DPG-210X controllers can be used on both diesel and gas engines. They can operate over a frequency range of 1000 to 11,000 Hz, and over a nominal voltage range of 9 to 30 Vdc.

Models in the series are DPG 2102, DPG-2103, DPG 2104, DPG-2105, and DPG 2107.

Engine governing is adjustable over a wide range of engine set speeds. An engine's set speed, also known as its target speed, can be any frequency from 1,000 Hertz to 11,000 Hertz. The following formula shows the relationship between engine rpm and Hertz.

(MPU signal in Hertz) = (Engine rpm) x (# of Flywheel Teeth) 60 sec

A magnetic pickup or MPU provides the engine speed signal to the controller in Hertz. The controller compares this signal to the user's programmed set speed, also in Hertz, to determine whether fuel to the engine needs to increase or decrease in order for the engine speed to equal the target speed.

The fuel flow is controlled with an actuator. The actuator may be part of a throttle body or connected to a separate throttle body with mechanical linkage. The controller provides a drive signal to the actuator to cause more or less fuel to flow through the throttle body thus affecting the engine's speed.

Features

- Isochronous speed control
- User friendly / operator adjustable
- Precision frequency control: 0.25%
- Superior temperature stability
- Reverse battery protection
- Input voltage range: 9–30 Vdc

Actuator Compatibility

Table 1-1. Actuator Compatibility

DYNA 2000	DYNA 70000	DYNA 8000	APECS 0150
DYNA 2500	DYNA 70025	DYNA 8200	APECS 0250
	DYNA 10141	DYNA 8400	APECS 0300
			APECS Linkage
			Free Integral
			Туре

Chapter 2. Specifications

The controller's main electrical and mechanical specifications are listed below along with several performance characteristics.

Operating Voltage Range	9–30 Vdc *	
Rated Output Current	7 A Maximum (continuous)	
Maximum Surge Current	14 A (not to exceed ten seconds)	
Temperature Stability	0.007 Hz @ 158°F (70 °C)	
Connections	Euro style terminal strip	
Input Signal: Startup Normal Operation	0-1000 Hz 1000-11,0000 Hz	
Input Signal from the Magnetic Pickup	2.5 VAC RMS minimum during cranking	
Input Signal from Engine's Ignition System	40 V minimum during cranking	

(*) All cabling for this unit is limited to less than 30m (98.4'). Power cabling is limited to less than 10m (32.8') in total length. See wiring diagrams for specific cable types required.

Ambient Operating Temperature	-40 °F to +180 °F (-40 °C to +82 °C)		
Sealing	Oil, water, and dust resistant via conformal coating and die cast enclosure		
Weight	0.6 lbs (28 kg)		
Table 2-3. Performance Specifications			

Steady State Speed Band	± 0.25% over ambient operating temperature range	

Temperature Stability 0.007 Hz @ 158 °F (70 °C)

User Interface Operation

Keypad

DPG-210X controllers provide two buttons for adjusting the engine set speed.

- INC increases the Set Speed
- DEC decreases the Set Speed

Gain Potentiometer

The DPG-210X controller provides a potentiometer (labeled GAIN) for two separate adjustments:

- Overall gain setting
- Integral limit setting

LED

The LED (Light Emitting Diode) is used as a status and operating indicator. When the LED is off, it indicates that one of the following is true:

- The unit is not being powered.
- The unit is reverse powered (check polarity of supplied power).

If a voltage between 9 Vdc and 30 Vdc is being properly supplied across the BAT+ and BAT- connector pins of the controller and the LED is off, then refer to the troubleshooting chapter.

A slow-blinking LED indicates all of the following:

- The unit is powered.
- The unit is in the GAIN ADJUST MODE (the gain setting can be adjusted).
- There is no MPU (Magnetic Pick-Up) signal. This means the engine is not running. If the engine is running and the LED is blinking slow then refer to the troubleshooting chapter for help in diagnosing why the MPU signal to the controller is missing.

A fast-blinking LED indicates all of the following:

- The unit is powered.
- The unit is in the GAIN ADJUST MODE (the gain setting can be adjusted).
- There is an engine speed signal at the controller's MPU terminals.

When the LED is on and not blinking it indicates the following:

- The unit is powered.
- The unit is in INTEGRAL LIMIT ADJUST MODE. The integral limit setting can be adjusted. In this operating mode it is not evident from the LED whether the engine is running or not.

NOTE: The slow blink rate = 1/2 Hertz (the LED is turned on for 1 second followed by off for 1 second then on again and so on). The fast blink rate is 3 times faster than the slow blink rate.



Chapter 3. Parameter Reference

DPG-210X controllers have three user-adjustable parameters: Set Speed, Gain, and Integral Limit. Table 3-1 shows the factory, minimum, and maximum settings for these parameters.

Parameter	Factory Setting		Minimum Setting	Maximum Setting
Set Speed	1,000 Hertz		1,000 Hertz	11,000 Hertz
Gain	20%		1%	100%
Integral Limit	DPG-2102 DPG-2103 DPG-2104	75%	20%	100%
	DPG-2105	76%	_	
	DPG-2107	50%	_	

Table 3-1. DPG-210X Parameter Settings

Table 3-2. DPG-210X PID Factory Settings

Model	Kp Proportional Gain	Ki Integral Gain	Kd Derivative Gain
DPG-2102	0.66	1.46	0.022
DPG-2103	0.38	0.8	0.02
DPG-2104	0.9	2.0	0.036
DPG-2105	1.0	1.4	0.15
DPG-2107	0.45	0.4	0.04

Set Speed and Gain Settings

The SET SPEED and GAIN adjustments work together. These adjustments are made while the engine is running.

NOTE: The factory setting for the SET SPEED is 1000 Hertz. The factory setting for the GAIN potentiometer is 20%.

The INC and DEC buttons are active whenever the controller is powered. The set speed is increased using the INC button. A momentary INC button press and release will increase the set speed by 1 Hertz. Press and hold the INC button to increase the set speed rapidly. The set speed is decreased using the DEC button.

The gain adjustment is used to modify how fast the controller responds to engine speed changes due to changing loads on the engine. Higher gain settings are more sensitive to changes in engine speed than are lower gain settings. Gain settings too high or too low can hinder the controller's ability to maintain a steady engine speed at the set speed.

As a general rule low set speeds require low gain settings. Likewise, higher set speeds require higher gain settings. For example: A set speed of 5040 Hertz will typically require a gain setting between 40% and 60% while a set speed of 3000 Hertz often works best with a gain setting between 20% and 40%.

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GAIN ADJUST MODE is active when the LED is blinking either fast or slow. If the controller is powered and the LED is on and not blinking the controller is currently in INTEGRAL LIMIT ADJUST mode. To put the controller back in GAIN ADJUST MODE do one of the following:

- Turn the power to the controller off then back on, or
- Press and hold, for approximately 5 seconds, both the INC and DEC buttons until the LED starts blinking then release the buttons.

Adjusting Engine Set Speed and Gain Setting Together

The DPG-210X is a very versatile controller. The speed range is 1000 Hz to 11,000 Hz. The wide range of speed adjustment also has wide range of gain adjustments. The speed adjustment and gain adjustment ranges are in direct relationship with each other. Therefore, when adjusting the controller speed it will be necessary to adjust gain also.



Controllers are factory adjusted to 1000 Hz.



An independent overspeed shut down device is required to prevent loss of engine control which may cause personal injury and/or equipment damage.

Procedure

Please read this entire procedure before making any adjustments.

- 1. With no power to the governor, verify that gain is set to 20% or factory default.
- 2. Start the engine and adjust the speed by pressing increase/decrease speed buttons until targeted speed is achieved or engine begins to hunt. Use a customer-supplied tachometer or frequency meter to verify speed.
- 3. If the engine begins to hunt adjust the gain to remove the hunt. The isochronous governor holds a fixed speed. If the engine varies speed slowly (oscillation rate < 1Hz) then increase the gain (in small increments) until oscillation disappears. For a fast hunt, which is defined as a 1Hz or greater oscillation, decrease the gain in small increments. This adjustment may need to be made as engine speed is adjusted to the target speed.</p>
- 4. Once the engine is set to the target speed it will be necessary to upset the engine governor to verify the performance of the system. This can be done by a very fast interruption (too long may cause shutdown) of the MPU + signal from the terminal or by bumping the linkage if available.
- 5. If after the engine governor has been upset, the engine begins to hunt, adjust the gain. For a slow hunt increase the gain, if the hunt is fast decrease the gain. If the engine response is slow, slowly increase the gain at 1/2-division increments. If the engine droops at full load, decrease the gain until the frequency is at target. When gain adjustments are made it will be necessary to recheck the performance of the engine by repeating Step 4. This will help set the governor response to fuel burn rate of the engine.

Integral Limit Setting

The INTEGRAL LIMIT is another adjustment that is available. The integral limit setting should only be adjusted when the engine is not running.



The integral limit feature may be useful in minimizing engine speed overshoot related to integral windup. When the engine is unable to carry a load the integral term of the PID equation will continue to grow which can cause a delay in reducing fuel to the engine when the load is removed or reduced.

The INTEGRAL LIMIT setting is used to stop integration whenever the actuator drive signal is above a specific percentage of the maximum signal possible. In the INTEGRAL LIMIT ADJUST MODE the potentiometer is used to set the actuator drive signal percentage above which integration is stopped.

INTEGRAL LIMIT ADJUST MODE is active when the LED is not blinking and on. See the following procedure for instructions describing how to adjust the integral limit setting.

Adjusting the Integral Limit

The engine should not be running when adjustments to the integral limit are made.

Follow the steps below to adjust the integral limit.

- 1. Apply power to the governor.
- 2. Record the current GAIN potentiometer setting.
- 3. Press both the DEC and INC buttons simultaneously for at least 5 seconds and the LED will stop flashing and remain turned ON.
- 4. The system is now in the INTEGRAL LIMIT adjust mode and the buttons can be released.
- 5. Turn the potentiometer to the desired position; for example to set the INTEGRAL LIMIT to 50% adjust the GAIN potentiometer to 50.
- 6. Press both the DEC and INC buttons simultaneously for at least 5 seconds and the LED will start flashing again.
- 7. The system has now been returned to the GAIN adjust mode and the buttons can be released.
- 8. Return the GAIN potentiometer to the setting recorded in Step 3.

INTEGRAL LIMIT adjustment is now complete.

Chapter 4. Installation

Recommended Mounting

The DPG-210X controller is designed to be panel mounted and its chassis electrically bonded to the same protective reference as the engine structure. The mounting location should protect the controller from exposure to rain, weather, and direct sunlight. The controller should not be mounted on the engine or in an environment that exceeds the mechanical specifications outlined in Chapter 2 of this manual.

Terminal Descriptions

No.	Terminal Name	Function
1	BAT+	Battery positive (9–30 Vdc)
2	BAT-	Battery negative
3	ACT	Actuator drive output
4	ACT	Actuator drive return
5	MPU+	Magnetic pickup signal input
6	MPU-	Magnetic pickup ground
7	SHIELD	Ground connection for cable shielding

Table 4-1 Terminal Functions

Wiring Diagram

IMPORTANT Cabling for the DPG 210X controller is limited to less than 3m (9.84'). Power cabling is limited to less than 10m (32.8') in total length. The wiring diagram below shows specific cable types required.



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Dimensions are in inches. [Dimensions in brackets are millimeters.]



Connect the MPU shield at the controller end only. Connecting the shield at the MPU source end could introduce noise due to ground loops and also disable the reverse battery protection feature.



NOTICE	To prevent damage to the controller, make sure that it is wired in accordance with the wiring instructions and diagrams in this manual.
	 Do not tin the leads before placing them into the terminals. Ensure the terminals are tightened properly to secure wires.

Centralized Suppression

The control meets the regulatory requirements for its intended installations, and when installed correctly as directed, the DPG input power can handle some level of surge pulses.

Because the control power input is designed to be connected to a local bus and to have inductive load kickbacks suppressed, it cannot withstand a charging system load dump, heavy inductive kickbacks, or heavy surge pulses.

- Charging system load dump is a pulse created when a heavily charging battery that is being charged by an alternator or generator (or similar), is disconnected from the bus.
- Inductive kickbacks are due to series or parallel switched, unsuppressed, inductive loads switched ON and OFF wired on the same power bus.
- Large surge pulses are typically due to indirect lightning strikes. Some surge pulses may also be present due to series inductances with switched currents.

The EMC environment into which the control is installed may have the above conditions if the control is installed OUTSIDE its intended usage. If the stated conditions exist, centralized pulse suppression should be implemented to protect the components on the bus, including the control.

Figure 4-2 is an example of centralized suppression that should be implemented at the system level when any of the following are present:

- The battery can be disconnected and an unsupressed high current battery charging system is in use.
- Unsuppressed, switched inductive loads are in parallel or series with the control power.
- The input power is derived from a distribution system or it is more than 32.8' (10m) from the control to the main power source





Figure 4-2. Centralized Suppression Implemented at the System Level

FIGURE NOTES:

- 1. Power and return cables to the control are routed together to minimize the noise pickup and emissions. Similarly, the power and return to the actuator must also be routed together but may be separated from the control's power leads.
- 2. MOV and TVS suppression devices are recommended based on the typical pulse levels that might be seen in Group 1 or Group 2 engine applications and the internal circuitry of the control.
- 3. Other suppression devices may be used, but clamping voltages and energy handling capability are important, as operating voltage and energy handling capability requirements depend on the full system implementation.

Examples:

- a) Two 15KP17CA and V47ZA7 through-hole parts are available from Woodward as 8923-1272.KIT. This kit is for a 24V system. It will suppress alternator load dump from alternators within the 200A range, as well as indirect lightning pulses that may be coupled to the power bus. Parallel inductive loads still need to be suppressed because pulses from unsuppressed parallel loads will be clamped at voltages too high to protect the control.
- b) Two 15KP13CA and one V47ZA7 through-hole parts are available from Woodward as 8923-1271.KIT. This kit is for a 12V system with an alternator within the 100A range, unsuppressed switched inductive loads in parallel with the control, and indirect lightning pulses that may be coupled to the power bus.
- 4. Suppression kits available from Woodward are intended to suppress the majority of the likely pulses. However, they will not protect against all system level implementations outside the intended usage of the control. A system level evaluation of what pulses may be present should be undertaken.

Please see Application Note 51319 for more details.

Chapter 5. Diagnostics & Troubleshooting

Table 5-1. Troubleshooting Chart

Symptom	Detection	Corrective Action
System appears dead: No LED, fails to move actuator.	Check battery voltage at controller with power switch turned ON. Measure DC battery voltage between (Bat + and Bat -)	If no voltage, check connections to battery.
	Check polarity of the Bat + and Bat -	Correct wiring
LED blinking slow and engine being cranked.	Check linkage. Manually operate linkage to see that it is not sticking or binding.	Free linkage.
	No signal or weak signal from magnetic pickup. Measure AC voltage between terminals MPU + and MPU – on the controller while cranking engine. Voltage should be 2.5 volts RMS or greater. (AC input impedance of meter must be 5000 ohms.)	Check for damage to or improper adjustment of magnetic pickup. Replace or readjust.
LED blinking fast but actuator does not move to open.	 Check actuator output with power ON to controller. Measure the following terminals on the controller box with respect to Bat All points should read Battery (+/- 95%) A) 1. Act to Bat - = Battery voltage 2. Act to Bat - = Battery voltage (± 1.5 Vdc) 	Replace controller if 95% of battery voltage is not present.
	B) Following checks are terminals	Check for broken actuator lead
	 controller. 1. Low voltage (1.0-2.0 Vdc) at either actuator terminal 2. Battery voltage at both actuator connectors 3. Battery voltage at one actuator lead but not at the other 	Check actuator
Actuator lever goes to full fuel whenever the power is turned ON and engine is not running.	 Check controller and actuator wiring 1. Turn off power to controller 2. Remove wiring to actuator terminals on controller and measure resistance between each lead and chassis ground. 0.0 ohms indicates shorted leads. 3. Normal resistance 	Correct or replace actuator wiring. Replace controller because it should not cause actuator lever to go to full fuel with engine not running.

Symptom	Detection	Corrective Action
Engine hunts during operation. (External linkage)	Linkage or rod end bearing sticking or binding.	Lubricate or replace
	Improper linkage arrangement. (Stroke too short or improper non- linear linkage used)	See installation chapter
	Improper governor adjustment	Readjust calibration
Engine hunts during operation. (Internal/External linkage)	 Inadequate power supply voltage. Turn power switch OFF. Remove actuator leads from controller. Connect actuator leads to Bat+ and Bat- direct to battery. Actuator should go to full fuel. 	Turn power switch OFF. Remove actuator leads from controller. Connect actuator leads to Bat+ and Bat- direct to battery.
	Internal style actuator should give a click noise when actuator hits the stops.	
	External style actuator should be visibly in the fuel position.	If actuator doesn't make full fuel, then check actuator leads.
	The actuator should go to full fuel and the DC voltage must be greater than 80% of supply. 24 Vdc @ 80% = 19.2 Vdc 12 Vdc @ 80% = 9.6 Vdc	check for loose or poor connections to battery, or get larger supply leads or larger power supply.
	NOTE: With the power switch in the OFF position, remove actuator leads from battery and reconnect actuator leads to controller when testing is completed.	

Table 5-1. Troubleshooting Chart (cont'd.)

Chapter 6. Product Support and Service Options

Product Support Options

If you are experiencing problems with the installation, or unsatisfactory performance of a Woodward product, the following options are available:

- Consult the troubleshooting guide in the manual.
- Contact the manufacturer or packager of your system.
- Contact the Woodward Full Service Distributor serving your area.
- Contact Woodward technical assistance (see "How to Contact Woodward" later in this chapter) and discuss your problem. In many cases, your problem can be resolved over the phone. If not, you can select which course of action to pursue based on the available services listed in this chapter.

OEM or Packager Support: Many Woodward controls and control devices are installed into the equipment system and programmed by an Original Equipment Manufacturer (OEM) or Equipment Packager at their factory. In some cases, the programming is password-protected by the OEM or packager, and they are the best source for product service and support. Warranty service for Woodward products shipped with an equipment system should also be handled through the OEM or Packager. Please review your equipment system documentation for details.

Woodward Business Partner Support: Woodward works with and supports a global network of independent business partners whose mission is to serve the users of Woodward controls, as described here:

- A **Full Service Distributor** has the primary responsibility for sales, service, system integration solutions, technical desk support, and aftermarket marketing of standard Woodward products within a specific geographic area and market segment.
- An **Authorized Independent Service Facility (AISF)** provides authorized service that includes repairs, repair parts, and warranty service on Woodward's behalf. Service (not new unit sales) is an AISF's primary mission.

A current list of Woodward Business Partners is available at www.woodward.com/local-partner

Product Service Options

The following factory options for servicing Woodward products are available through your local Full-Service Distributor or the OEM or Packager of the equipment system, based on the standard Woodward Product and Service Warranty (5-09-0690) that is in effect at the time the product is originally shipped from Woodward or a service is performed:

- Replacement/Exchange (24-hour service)
- Flat Rate Repair
- Flat Rate Remanufacture

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Replacement/Exchange: Replacement/Exchange is a premium program designed for the user who is in need of immediate service. It allows you to request and receive a like-new replacement unit in minimum time (usually within 24 hours of the request), providing a suitable unit is available at the time of the request, thereby minimizing costly downtime. This is a flat-rate program and includes the full standard Woodward product warranty (Woodward Product and Service Warranty 5-09-0690).

This option allows you to call your Full-Service Distributor in the event of an unexpected outage, or in advance of a scheduled outage, to request a replacement control unit. If the unit is available at the time of the call, it can usually be shipped out within 24 hours. You replace your field control unit with the like-new replacement and return the field unit to the Full-Service Distributor.

Charges for the Replacement/Exchange service are based on a flat rate plus shipping expenses. You are invoiced the flat rate replacement/exchange charge plus a core charge at the time the replacement unit is shipped. If the core (field unit) is returned within 60 days, a credit for the core charge will be issued.

Flat Rate Repair: Flat Rate Repair is available for the majority of standard products in the field. This program offers you repair service for your products with the advantage of knowing in advance what the cost will be. All repair work carries the standard Woodward service warranty (Woodward Product and Service Warranty 5-09-0690) on replaced parts and labor.

Flat Rate Remanufacture: Flat Rate Remanufacture is very similar to the Flat Rate Repair option with the exception that the unit will be returned to you in "like-new" condition and carry with it the full standard Woodward product warranty (Woodward Product and Service Warranty 5-09-0690). This option is applicable to mechanical products only.

Returning Equipment for Repair

If a control (or any part of an electronic control) is to be returned for repair, please contact your Full-Service Distributor in advance to obtain Return Authorization and shipping instructions.

When shipping the item(s), attach a tag with the following information:

- Return authorization number
- Name and location where the control is installed
- Name and phone number of contact person
- Complete Woodward part number(s) and serial number(s)
- Description of the problem
- Instructions describing the desired type of repair

Packing a Control

Use the following materials when returning a complete control:

- Protective caps on any connectors
- Antistatic protective bags on all electronic modules
- Packing materials that will not damage the surface of the unit
- At least 100 mm (4 inches) of tightly packed, industry-approved packing material
- A packing carton with double walls
- A strong tape around the outside of the carton for increased strength



To prevent damage to electronic components caused by improper handling, read and observe the precautions in Woodward manual 82715, *Guide for Handling and Protection of Electronic Controls, Printed Circuit Boards, and Modules.*



Replacement Parts

When ordering replacement parts for controls, include the following information:

- The part number(s) (XXXX-XXXX) that is on the enclosure nameplate
- The unit serial number, which is also on the nameplate

Engineering Services

Woodward offers various Engineering Services for our products. For these services, you can contact us by telephone, by email, or through the Woodward website.

- Technical Support
- Product Training
- Field Service

Technical Support is available from your equipment system supplier, your local Full-Service Distributor, or from many of Woodward's worldwide locations, depending upon the product and application. This service can assist you with technical questions or problem solving during the normal business hours of the Woodward location you contact. Emergency assistance is also available during non-business hours by phoning Woodward and stating the urgency of your problem.

Product Training is available as standard classes at many of our worldwide locations. We also offer customized classes, which can be tailored to your needs and can be held at one of our locations or at your site. This training, conducted by experienced personnel, will assure that you will be able to maintain system reliability and availability.

Field Service engineering on-site support is available, depending on the product and location, from many of our worldwide locations or from one of our Full-Service Distributors. The field engineers are experienced both on Woodward products as well as on much of the non-Woodward equipment with which our products interface.

For information on these services, please contact one of the Full-Service Distributors listed at <u>www.woodward.com/local-partner.</u>

Contacting Woodward's Support Organization

For the name of your nearest Woodward Full-Service Distributor or service facility, please consult our worldwide directory at <u>https://www.woodward.com/support</u>, which also contains the most current product support and contact information.

You can also contact the Woodward Customer Service Department at one of the following Woodward facilities to obtain the address and phone number of the nearest facility at which you can obtain information and service.

Products Used in	
Electrical Power Systems	
Facility Phone Number	
Brazil+55 (19) 3708 4800	
China+86 (512) 8818 5515	
Germany+49 (711) 78954-510	
India+91 (124) 4399500	
Japan+81 (43) 213-2191	,
Korea+82 (32) 422-5551	
Poland+48 (12) 295 13 00	•
United States+1 (970) 482-5811	

Products Used in Engine Systems

Facility Phone Number
Brazil+55 (19) 3708 4800
China +86 (512) 8818 5515
Germany +49 (711) 78954-510
India+91 (124) 4399500
Japan+81 (43) 213-2191
Korea+ 82 (32) 422-5551
The Netherlands+31 (23) 5661111
United States+1 (970) 482-5811

Products Used in Industrial Turbomachinery Systems

Facility Phone Number
Brazil +55 (19) 3708 4800
China +86 (512) 8818 5515
India+91 (124) 4399500
Japan+81 (43) 213-2191
Korea+ 82 (32) 422-5551
The Netherlands+31 (23) 5661111
Poland+48 (12) 295 13 00
United States+1 (970) 482-5811

Revision History

Changes in Revision C-

- Removed EPG 512 and EPG 1724 from Table 1-1
- Added Lockout/Tagout and IOLOCK warnings (pages 3 & 4)
- Updated Electrostatic Discharge Awareness section (page 5)
- Updated Product Support section (Chapter 8)

Released

Declarations

DECLARA	TION OF CONFORMITY
Manufacturer's Name:	WOODWARD GOVERNOR COMPANY (WGC)
Manufacturer's Address:	1000 E. Drake Rd. Fort Collins, CO, USA, 80525
Model Name(s)/Number(s):	DPG-210X Series
Conformance to Directive(s):	2004/108/EC COUNCIL DIRECTIVE of 15 December 2004 on the approximation of the laws of the Member States relating to electromagnetic compatibility and all applicable amendments.
Applicable Standards:	EN61000-6-4, (2007): EMC Part 6-4: Generic Standards - Emissions for Industrial Environments
	EN61000-6-2, (2005): EMC Part 6-2: Generic Standards - Immunity for Industrial Environments
We, the undersigned, hereby declare tha	t the equipment specified above conforms to the above Directive(s).
Engineering Manager Position WGC, Fort Collins, C Place 7/24/09 Date	20, USA



We appreciate your comments about the content of our publications.

Send comments to: industrial.support@woodward.com

Please reference publication 36543.





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Email and Website—<u>www.woodward.com</u>

Woodward has company-owned plants, subsidiaries, and branches, as well as authorized distributors and other authorized service and sales facilities throughout the world.

Complete address / phone / fax / email information for all locations is available on our website.