

LeoPC1 User Manual

User Manual Software Version 3.1.2

37146C

WARNING

Read this entire manual and all other publications pertaining to the work to be performed before installing, operating, or servicing this equipment. Practice all plant and safety instructions and precautions. Failure to follow instructions can cause personal injury and/or property damage.

The engine, turbine, or other type of prime mover should be equipped with an overspeed (overtemperature, or overpressure, where applicable) shutdown device(s), that operates totally independently of the prime mover control device(s) to protect against runaway or damage to the engine, turbine, or other type of prime mover with possible personal injury or loss of life should the mechanical-hydraulic governor(s) or electric control(s), the actuator(s), fuel control(s), the driving mechanism(s), the linkage(s), or the controlled device(s) fail.

Any unauthorized modifications to or use of this equipment outside its specified mechanical, electrical, or other operating limits may cause personal injury and/or property damage, including damage to the equipment. Any such unauthorized modifications: (i) constitute "misuse" and/or "negligence" within the meaning of the product warranty thereby excluding warranty coverage for any resulting damage, and (ii) invalidate product certifications or listings.

CAUTION

To prevent damage to a control system that uses an alternator or battery-charging device, make sure the charging device is turned off before disconnecting the battery from the system.

Electronic controls contain static-sensitive parts. Observe the following precautions to prevent damage to these parts.

- Discharge body static before handling the control (with power to the control turned off, contact a grounded surface and maintain contact while handling the control).
- Avoid all plastic, vinyl, and Styrofoam (except antistatic versions) around printed circuit boards.
- Do not touch the components or conductors on a printed circuit board with your hands or with conductive devices.



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Important definitions



WARNING

Indicates a potentially hazardous situation that, if not avoided, could result in death or serious injury.

CAUTION

Indicates a potentially hazardous situation that, if not avoided, could result in damage to equipment.



NOTE

Provides other helpful information that does not fall under the warning or caution categories.

Woodward reserves the right to update any portion of this publication at any time. Information provided by Woodward is believed to be correct and reliable. However, Woodward assumes no responsibility unless otherwise expressly undertaken.

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Revision History

-	~		a:
Rev.	Date	Editor	Changes
С	2013-11-25	GG	No new functional features.
			Software version LeoPC1 V3.1.2 now is Windows XP, Windows 7, and Windows 8 compatible.
			Manual
			Updated for changes driven by the additional operating systems.
			Address and typo corrections.
В	2007-09-05	MH	Updated for new software version LeoPC1 V3.1.1
А	2004-09-09	MH	Updated for new software version LeoPC1 V3.1
NEW	2002-10-17	MH	Release of software version LeoPC1 V3

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Chapter 1. **General Information**

General Points

LeoPC1 provides you with a Windows-based program for your PC or laptop that offers support for the handling of selected measuring instruments as well as open-loop and closed-loop control devices. The following functions are supported they are installed on the device as well:

of measured variables or the logical statuses of your plant
of the configurable devices used in your plant
of your devices can be stored for reloading or transferring
of the controllable devices used in your plant
of selected data and measured values or events of your plant
of the corresponding devices can be read out and printed
management and loading for the display of your adaptable devices
logging, management and preparation for your plant

The devices differ in level of support:

1 1 2

Full	support of all functions
Limited	support of the functionality
No	device not supported

The degree of **support** depends on the product the year of manufacture, and what external devices are to be used with the product.



NOTE

Please refer to the corresponding documentation for the specific devices to see what support utilities your devices permits in terms of operator control with the LeoPC1.

LeoPC1 utilizes permits management of access rights. These access rights are graduated in the degree of access to the programming. It is differentiated between:

Administrative	access to all functions and settings is permitted
Level 2 authorized	access to all functions permitted
Level 1 authorized	access to data logging functions only
Access denied	access to all functions and settings are blocked

Should a component described in this manual not be available, please contact your system administrator. The system administrator will be able to provide you with the advice you require.

The LeoPC1 is obtainable in the following version:

Full version LeoPC1 with full functionality:

- CAN bus driver (allows all functions via a CAN card connection)
- Gateway RS-232 driver (allows all functions via a Gateway connection) •
- Modem driver (allows all functions via a modem connection)
- Direct driver (only for configuration via the direct connection)
- Demo driver (for demonstration purposes without a connected device) •

Helpful Information about the Manual

This manual provides for a **first-time user** explanatory introduction to:

Commissioning:	Installation, uninstalling, and general configuration
Properties:	of all functions and their application
Communication	
Connection:	Drivers and communication utilities of the LeoPC1.

The individual **sections** are structured so that you are provided with each of the following for each program segment:

Introduction	to specific functions and their significance
Explanation	of the individual components in terms of their functionality
Description	of the procedure, broken down into individual steps.

Provided in addition with the descriptions of the procedure are:

Illustrations

that permit cross-referencing to the relevant screens and menus of the LeoPC1.

NOTE

Information captions contain general, important items of information, additional specifications and/or references to more extensive sources of information.



Comments additional explanatory comments are printed in "()"

For more detailed questions regarding the LeoPC1, please contact our support team.

Chapter 2. Commissioning

The following version of the LeoPC1 is available:

The full version

comprises the following components: Application (minimum requirement) Demo driver Direct driver IXXAT VCI – CAN bus-driver Modem driver Gateway RS-232 driver

LeoPC1 can be easily installed from your CD-ROM drive. It is a one-click installation. The IXXAT driver that works with the current LeoPC1 software can be installed from the CD-ROM, too. A detailed explanation of the installation and configuration process is located in the following section.

Installation

During installation numerous components are installed in your PC due to the multiple versions of LeoPC1 with differing functionalities. If there are controllers that have been configured with LeoPC1 v2.x or earlier version, they <u>cannot</u> be reconfigured with later versions of LeoPC1. STD files created by LeoPC1 v2.x or earlier version are not compatible with LeoPC1 v3.x and higher.

This version will be installed in a different directory than LeoPC1 v2.x or earlier version by default and can be launched by a different entry than LeoPC1 v2.x or earlier version in the start menu.

Versions 2.x cannot be run after setting up a new version. Due to this it is recommended to uninstall any version 2.x or earlier of LeoPC1 before setting up this new version.

If an IXXAT VCI driver version lower than 3.5.1 is installed on your PC/laptop, e.g. it was installed with LeoPC1 version 2.x or 3.0, you are recommended to follow the instructions given from IXXAT.de to remove the old VCI version with their tool vciclean.exe before installing the new IXXAT VCI driver from CD-ROM or IXXAT website.

Components of the Installation

The full version enables you to perform data transfers for the purpose of display, configuration and control via a special CAN bus, modem, RS-232, or a direct connection.

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NOTE

For detailed information on the relevant files to be installed and in which directory they are to be found is located in the annex of this manual; see page 88 ff.

The following files and sub directories will be found in the main program menu directory:

- Files System files "*.*", configuration files "*.cfg", event memory files "*.dat", and files for external tools.
- Alarms\ For daily alarm protocols "01.alm" to "31.alm"
 - **DL**\ For temporary data-logging files "DLx.tmp", where x stands for the device number
- Lng\ For the load language files "*.lng"
- Pictures\ For the bit map layout files "*.bmp"
- Std\ For the standard value files "*.std"
- **Tools**\ For the assembler "*.asm" and option files "*.opt" used with the configuration files

NOTE

Temporary files are created for each connected device and are used to display the configured values after exiting or in the event of an application crash for restarting the LeoPC1. These files are lost when a new configuration is started.

LeoPC1 can be installed on all Microsoft Windows[©]-systems. When installing LeoPC1 the following requirements must be followed:

Windows XP/ Administration rights for the computer to have the program installed.Windows 7/ The operator for the program will require main user rights to the computer at

Windows 8 a minimum.

The required hard drive space for installing LeoPC1 is dependent on the application modules of the version to be installed:

The program will require between 20 and 60 MB of storage space.



NOTE

These specifications are minimum specifications and relate to the LeoPC1 itself.

This specification does not account for storage space that will be required by the configuration, data logging, alarm management files and all other files created for the use of this software tool.

i NOTE

LeoPC1 is supporting CAN connection via IXXAT CAN interface.

An IXXAT driver version that works with the current LeoPC1 version can be installed from the CD-ROM via menu or file selection. The minimum version of the IXXAT driver file is:

vci_3_5_1_3826.exe

Procedure for Installation

The LeoPC1 software installation is a one-click process following the Windows standard, just running through your PC/laptop Windows installation dialog with its

- safety alerts,
- request(s) to accept installation, and
- check boxes to trust the publisher (Woodward).

LeoPC1 installation is asking for language selection only.

If installing LeoPC1 from a

- Woodward CD-ROM, the menu offers LeoPC1 installation to be selected.
- (downloaded) file from Woodward website.

Start installation	Insert the CD-ROM into the CD/DVD drive, start the CD-ROM menu, and
or	select "LeoPC1" download the LeoPC1 installation file from Woodward website, locate the installation file with your file manager, and double click on ((open)) "LeoPC1 3 1.2 msi"
The installation screen appears	Dateidownload
	Dateidownload - Sicherheitswarnung
	Möchten Sie diese Datei speichern oder ausführen? Name: LeoPC1 3.1.2.msi Typ: Windows Installer-Paket, 3,91 MB Von: X:\37134_Manual [SMP-D10_YB]\leopc1 Ausführen Speichern
	Dateien aus dem Internet können nützlich sein, aber dieser Dateityp kann eventuell auf dem Computer Schaden anrichten. Führen Sie diese Software nicht aus und speichem Sie sie nicht, falls Sie der Quelle nicht vertrauen. Welches Risiko besteht?

Click on "Ausführen".



NOTE

LeoPC1 installation is an automated process, just asking for the language to be installed. Please allow Woodward to install the software if you are asked by Windows User Account Control.



Select your preferred language (English or Deutsch or Portuguese). Click on "Install".

Accept publisher Woodward to install the software to your user account.



Click on "Yes". Woodward LeoPC1 files will be installed.

Figure 2.2 Accept changes/installation



```
Figure 2.4
New entry in Start program
```

Figure 2.5 New entry in Start / all programs





NOTE

If your application is using LeoPC1 communication via CAN bus, follow the driver installation instruction as described below.

Otherwise skip this chapter and continue on page 18 with chapter Start LeoPC1.

Procedure for Can bus Driver Installation

For communication via CAN bus using an IXXAT interface, please install the IXXAT VCI driver 3.5.1 (on CD-ROM) or higher (download it from IXXAT website):

Start installation Insert the CD-ROM into the CD/DVD drive,

start the CD-ROM menu, and

select "CAN interface (IXXAT)"

or download the current version (3.5.1 or higher) of the IXXAT vci driver installation file from IXXAT website 'www.ixxat.com'', locate the installation file with your file manager.



NOTE

IXXAT drivers distributed with Woodward CD-ROM are well tested but no Woodward product.

The service of providing a copy of a third party file does neither implement any liabilities nor any right of compensation for damages.

To install the IXXAT driver coming with the Woodward CD-ROM is described below; maybe newer updates differ.



Click on "Next".

Figure 2.7 Accept the IXXAT license agreement

cense Agreement	
Please read the following important ir	nformation before continuing.
Please read the following License Agr agreement before continuing with the	reement. You must accept the terms of this e installation.
*****	******
IXXAT Automation GmbH Leibnizstr. 15, 88250 Weingarten, G	ermany
May 30, 2008	
[German version below]	
 I accept the agreement 	
~ .	

Check "I accept the agreement and click on "Next"



Click on "Next".

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Click on "Install". The VCI driver for IXXAT CAN interfaces may now be installed.



Finish installation After (driver) installation you are asked to restart your computer, to ensure system working stable.

Please follow the proposal: Go with the default selection and restart the computer by a click on "Finish".

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NOTE

It is necessary to restart the PC/laptop after the completion of the installation of the IXXAT driver (and recommended anyway after every installation) to ensure the operating software is stored and all functions and links are properly enabled.

Start LeoPC1

After rebooting the PC/laptop, LeoPC1 may be started by following the log on procedure below:

To start the application: Click on:

- Start...Programs...Woodward... LeoPC1... LeoPC1
- or Via Windows-Explorer start the "main.exe" in the selected main directory
- or Start a "*.cfg" file in the selected main directory

It is recommended to copy the LeoPC1 start icon to the quick access bar: Click on the icon, hold left mouse button, move the icon to the quick access bar and locate it where you want.





NOTE

It is recommended that the system administrator change the password immediately after logging on the first time. Make note of the password issued to you, as most functions of LeoPC1 require this password for access.

If you attempt to utilize LeoPC1 prior to logging on, you will be prompted that logging on is required. By clicking on the "Yes" button the User Login dialog window will be displayed.



Procedure for Uninstalling

If you wish to remove LeoPC1 version on your PC, please use the Windows 7 de-installation routine.

To start uninstalling:	Click on Windows 7 "Start" button Select/click on "Control Panel" Click on "Uninstall a program" Select "LeoPC1" and click the "Uninstall/Change" button
Programme und Funktionen	
	Möchten Sie LeoPC1 wirklich deinstallieren?
	Diesen Dialog nicht mehr anzeigen Ja Nein
	Click on "OK"

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Loading a Plant Configuration



NOTE

Open your plant configuration from the actual application.

A plant configuration must be opened from the correct application file (**.asm). LeoPC1 must be started and the correct application file opened to begin configuring a plant.

Various plant configurations can be loaded with LeoPC1. The plant configuration functions and layout are dependent on the following:

Version of the LeoPC1 being used Devices that are to be communicated with Tasks that to be assigned to devices Requirements that the plant must meet

Basically it can be differentiated between:

- Demo configuration
- Direct parametric configuration
- Display configuration
- · Configuration and display configuration

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NOTE

Due to the numerous control units and possible combinations of these units, it is impossible to cover every plant configuration. Operator control will be discussed only in general terms because of this.

For further information on and examples of configurations, please refer to the following sections:

- "General Configuration" after page 26
- "Communication and Connection" after page 73

and the corresponding sections of the manuals for your specific control unit.

Some **prerequisites** have to be met before you can load your plant configuration (provided that it has not been done already by installation)

To copy files:	Use, for example, Windows-Explorer for this step:
	Copy the corresponding CFG configuration file (*.cfg) to the main menu in
	the LeoPC1 file folder
Pathway	C:\Program Files\Woodward\LeoPC1
and	Copy the pertinent ASM configuration file (*.asm, if necessary *.opt) to the
	sub-directory TOOLS in the LeoPC1 file folder
Pathway	C:\Program\Woodward\LeoPC1\Tools
	Copy and paste.



NOTE

In some versions of LeoPC1 (e.g. LeoPC1.cfg), it is possible to copy and paste configuration files from a floppy disk or a CD-ROM. If too many sub-directories are transferred at one time by this method, the possibility of errors occurring in the files is greatly increased.

To use copy tools:	Click on
	ToolGet Config
Figure 2.18	Tools ?
Open Tools menu	Get Config
and	Follow the directions in the dialog window that opens up
and	Select the desired configuration files from the disk, CD ROM, or file folder
	where they are located.
Figure 2.19	Browse for Folder
Search directory	Select source path:
	My Documents
	🗈 🖳 My Computer
	🗈 📴 My Network Places
	OK Cancel
and	Start the copy operation. A dialog window will open displaying the status of
	the files that were transferred. This may be acknowledged by clicking
	<u>o</u> k
To connect devices	For communication with the desired connection type
	(Depending on your device and plant configuration):
Demo connection	Connection to a device is necessary
Direct connection	COM port of the PC > Direct configuration cable > RJ45 port of the device
Gateway connection	COM port of the PC \Leftrightarrow Gateway RS-232 \Leftrightarrow Device.
	Device
CAN bus connection	CAN card COM port of the PC $>$ Adapter cable $>$ Device
	end composition de l'el contraction du de la period

Ensure that the COM port to be used for configuration has not been assigned to more than one function.

Read the documentation of the device to be configured prior to beginning the configuration of that unit.

All control units will require individual tuning to gain optimum performance within the plant. Some older control units require the configuration interface to be activated before configuration can be performed.

NOTE

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To activate devices: Configuration method	Turn power on to all devices to be configured.
Direct connection	On devices with a display set the direct configuration screen to "ON"
Gateway and modem connection	On devices with display set the direct configuration screen to " OFF " (the CAN bus interface is disabled when the direct configuration mode is enabled)
CAN bus connection	On devices with displays set the direct configuration screen to " OFF " (the CAN bus interface is disabled when the direct configuration mode is enabled)
To load a configuration:	Click on:
	StartProgramWoodwardLeoPC1LeoPC1 (application is started) <u>F</u> ileOpen(the "Open" file dialog window is opened)
	Or click the 🚰 icon.
and	Select the *.cfg file that has been copied to the main directory
or	Start the *.cfg file directly from the selected mains directory
Direct connection	Only used for configuration of the device. Display of the measured data may not be possible.
Gateway, modem or CAN bus connection	The device may be configured while measured data from the generator/ plant is displayed. Extreme caution must be exercised when configuring through this method.
To log on:	Click on: SystemUser Login(Only personnel with system administrator privileges may configure control units)
	Or click the icon.



NOTE

If no changes have been made to the user/password settings, the user ID and password for the system administrator will still be set as the default:

Name = "system"

Password = "system"

To select application modules:	Click on: DevicesSettings (Settings to parameterize system dialog window will
Figure 2.20	Devices View System ?
Open Device Settings	Load Language F7
	Select Enable Program Modules (changes the available configuration modules)

Figure 2.21	Settings to parameterize system
Enable Program Modules	General Options Service Configuration Enable Program Modules Image: Image Service Configuration Image Service Configuration Image: Image Service Control Image Service Control Image: Image: Image Service Control Image Service Control Image: Image: Image: Image Service Control Image Service Control Image: Image: Image: Image Service Control Image Service Control Image: Image: Image: Image Service Control Image Service Control Image: Image: Image: Image Service Control Image Service Control Image: Image: Image: Image Service Control Image Service Control I
	<u>QK</u> <u>Cancel</u> <u>Apply</u> Help
and	Enable the modules that will be required for the connection and tasks:
Direct configuration	The modules "Parameterize" and "standard values" are sufficient to config-
Cataway modem or	ure most control units generally.
CAN bus connection	that will be needed according to your requirements
	Click on \underline{Q}^{K} to save settings.
To select the communication type:	Click on:
.,per	DevicesSettings (The "Settings to parameterize system" dialog window
	will open)
Figure 2.22	Devices View System ?
Open Device Settings	Load Language F7

Select General Options

Figure 2.23	Settings to parameterize sy	stem X
General Options	General Options Service Con	figuration Enable Program Modules
	Paths and files	
	Path for alarm files:	ALARMS\
	<u>H</u> elp file for alarms:	
	Data communication	
	<u>D</u> river:	Direct
		Direct
	Start communication au	Madema Vici2 - CAN
	<u>R</u> emote control	not activated
	<u>D</u> isplays	deactivated while parameterizing/loading language
	Changes will be activated imm	rediately by submitting OK.
		<u>D</u> K <u>Cancel</u> <u>Apply</u> Help
and	Select the method of con	figuration to be used in the Data communication
	Driver box from the follo	owing:
Direct configuration	Driver: "Direct"	
Gateway connection	Driver: "Gateway RS-23	2"
modem connection	Driver: "Modem"	
CAN bus connection	Driver: "IXXAT VCI3 –	CAN"
Remote control	Set the remaining dialog	boxes as follows:
Displays	"Not active"	
	"Deactivate while param	eterizing/load language"
or	Set according to requirer	nents



NOTE

Refer to the product manual when selecting the baud rate for communications.

To connect: Click on:

Communication...Connect (The communication link between the PC/laptop and the device is established)



General Configuration

LeoPC1 may be configured in several different ways. For this purpose it is differentiated between:General configurationAdaptation of the system settings and the device settings to your plantSpecial configurationCreation of the *.cfg files and *.asm configuration files

NOTE

Special configuration is generally not necessary. Your supplier should have already performed all necessary adaptations to your plant and devices.

This special configuration is described in more detail in a separate manual 37164.

Components of the General Configuration



NOTE

Ensure that the general configuration described below can only be accessed/performed by experienced personnel through the use of the System administrator. Failure to do so may result in these settings will interfering with your PC operating system, the hardware configurations, and/or the plant configuration.

The components of the general configuration are subdivided into three areas:

System Configurations

Log on /log off user	Dialog window for logging on/off
User management	List of the user names, passwords, and access rights
System settings	Language settings and logging parameters
	Path variables for CFG-files

Plant Configurations

General options	Definition of the alarm path and of the alarm help file
and	definition of the data communication and connection settings
Service Configuration	Definition of parameters for the data buffer etc.
Enable program modules	Definition of the enable/disabled application modules

View Configurations

Symbol bars and settings Definition of the LeoPC1 window layout

Procedure for General Configuration

System Configurations

User

To log on:	Click on:		
Figure 2.24 Open User Login	SystemUser Login or click the Good icon. System ? User Login Alt+Shift+A User Management		
Editing boxes or and or	System Settings Name: "system" (visible as system), if the factory default has not been changed "User ID" (with administrative rights) Password: "system" (visible as ******), if the factory default has not been changed "User password"		
Figure 2.25 User Login	User Login Please enter a valid name and password Name: System Password: XXXXXX Click QK		
To open user management	Click on: SystemUser management (The user management dialog window will open)		
Figure 2.26 Open User Management	System ? User log off User Management System Settings		
To set up a user Editing boxes: and and Option:	Open user management and click on: "New user" and enter the desired user ID "Password" and enter the desired user password "Repeat" and verify the desired user password Click Set new user and the new user will appear in the Users List Highlight the desired user ID and click on "System admin." to assign full ac- cess rights to this user or the appropriate level of access at this time.		
	Confirm all changes made to users and access rights by clicking on OK		

Figure 2.27	Users Management
User Management	Users list □ Access denied □ System □ Access denied □ © System admin. □ Help ○ Level 2 authoriz. □ Level 1 authoriz. □ Delete □ □
	New user Password: Repeat Sgt new user

NOTE

A user ID can only be assigned one password and level of access at a time.

A user ID should be assigned the appropriate level of access when it is created. Only the highlighted user ID can have any changes made to the level of access or status. It is not possible to edit a password for an active user ID. A user ID that has been deleted cannot be edited or logged onto the system. User ID's that have been deleted can be re-entered as a new user ID if it is desired to use again.

To manage a user:	Open Users manager and click on:		
	Desired user name (scroll menu with all defined users)		
Desired options:	"Access denied" (denies access to a user)		
	"System admin." (Permits full access to system functions and settings)		
or	"Level 2 authoriz." (Permits access to system functions only)		
or	"Level 1 authoriz." (Permits access to data logging only)		
	Verify all changes by clicking the "OK" button.		
To delete a user	Open user management and click on:		
	Desired user name (scroll menu with all defined users)		
	Delete (The user is removed from the scroll menu)		

NOTE

Only one user can be logged onto LeoPC1 at any one time. If a user is logged on, he/she must log off to permit another user to log on to the application. The user ID of the signed on user is displayed at the

bottom right corner of the LeoPC1 window. The user may be logged off by clicking on the icon or using the "System" button in the tool bar and clicking on "Log off user"

System

Го open system settings	Select "System" from the Command menu, "System Settings…" from the drop down menu (the "System settings" dialog window will open), and click on:
Figure 2 28	System ?
Open System Settings	User log off
	User Management
	System Settings
	Settings tab (changes the displayed tab)
Figure 2.29	System settings
System Settings	Settings Paths
	Language: English
	Deutsch
	Start data loj Portuguese your system.
	Save data logging automatically while closing your system.
	in file:
	Catting for super-table langing flag
	Settings for export data logging files
	✓ Output heading line ?
	Seperater ;
	OK Cancel Apply Help

To define the language Select "System" from the Command menu, "System Settings…" from the drop down menu (the "System settings" dialog window will open), and click on:

Language: (pull down menu displays all available languages)

i

NOTE

The language defined in this parameter has no effect on a control unit that may be configured in a different language.

Example: If a control unit is configured in English and German is the language selected for this parameter, the control unit will continue to display all parameters in English while the same parameters will be displayed in the LeoPC1 program in German.

To define data logging:	Select "System" from the Command menu, "System Settings…" from the drop down menu (the "System settings" dialog window will open), and click on: Start data logging automatically upon loading the plant configuration Save data logging automatically upon closing the plant configuration
activate	Enter a check mark in the box next to the desired data logging option
deactivate	Remove the check mark in the box next to the data logging option to be de-
Saving data	Click on the file icon to open the "Save As" dialog window, type in the name of the file for the data, and select the file to save the data in. After a file name has been selected the Save button has been clicked, the pathway for the file will be displayed in text box. The OK at the bottom of the System settings dialog window must be clicked to accept any changes made to these settings.

NOTE

When saving data logging files, they must end in ".llo". All data logging files must use the "LLO" format.

drop down menu (the "Syst and click on: Under "setting for export d next to "Output header line Enter separator character (i	em settings" dialog window will open), ata logging files" enter a check mark in the box ?" t is recommended that a semicolon ";" be used).	
Select "System" from the Command menu, "System Settings…" from the drop down menu (the "System settings" dialog window will open), and click on:		
System ?		
User log off User Management		
System Settings		
	drop down menu (the "Syst and click on: Under "setting for export da next to "Output header line" Enter separator character (if Select "System" from the C drop down menu (the "Syst and click on: System ? User log off User log off User Management	

Paths tab (changes the displayed tab)

<u>37146C</u>

Figure 2.31 Path variables for CFG files	Settings Paths	×
	P <u>a</u> th variables for CFG-files	
	onfig Path ASM_PATH C:\Projects\Software\Tools BITMAP_PATH C:\Projects\Software\Pictures DL_PATH C:\Projects\Software\DL LNG_PATH C:\Projects\Software\LNG STD_PATH C:\Projects\Software\STD	
	Variable: ASM_PATH Path: C:\Projects\Software\Tools	
	<u>□</u> K <u>C</u> ancel <u>Apply</u> Help	



NOTE

As newly defined variables require an equivalent in the configuration file, it is not recommended adding or removing any path variables, but merely adapting the directories.

Example: If the configuration files were stored in a common file on a network so that they may be accessed from multiple computers instead of being stored on an individual computer, the pathway to the necessary CFG files would be modified here for the computer that will require access to these files.

To define paths:	Open the System settings dialog window and click on: Paths (changes the displayed page) Desired path variable for CFG file (selected variable is entered into the text box for editing) In the "Path:" text box enter desired path Click on the icon to open the "Select Path" dialog window and modify the pathway to the desired path	
Editing box or		
and	Click Set to enable the new path (the path is relocated to the path variable)	
To define the path variable	Click on:	
Editing boxes:	Click in the "Variable:" text box and enter the appropriate designation of the CFG file	
	Click in the "Path:" text box and enter desired path	
or	Click on the icon to open the "Select Path" dialog window and enter the desired path	
and	Click to enter the new path variable (the path variable is set and appears in the list box)	

General settings



NOTE

Any changes made to the General Options will take effect immediately after the dialog window is closed.

To open general settings	Select "Devices" from	the Command menu, "Settings" from the drop	
	down menu (the "Settin	igs to parameterize system" widow will open):	
Figure 2.32 Open Device Settings	Devices view System		
Open Device Settings	Load Language	F7	
	Settings		
Figure 2.33	Settings to parameterize s	system	×
General Options	General Options Service Co	onfiguration Enable Program Modules	
	Paths and files		
	Path for alarm files:	ALARMS\	
	Help file for alarms:		
		· · · · · · · · · · · · · · · · · · ·	
	Data communication		
	Driver:	Direct	
		<u>S</u> ettings	
	Start communication a	automatically while loading the system configuration	
	<u>R</u> emote control	not activated	
	<u>D</u> isplays	deactivated while parameterizing/loading language 💌	
	Changes will be activated in	nmediately by sybmitting OK	
		initialities by submitting of t	
		<u>OK</u> <u>Cancel</u> <u>Apply</u> Help	

To define communication:	Select "Devices" from the Command menu, "Settings…" from the drop down menu (the "Settings to parameterize system" dialog window will open), the "General Options" tab, and click on: Driver pull down menu: in Data communication and select the applicable			
	driver for your configuration method (all installed drivers will be displayed)			
Figure 2.34	Direct			
Drivers	Demo			
	Direct			
	IXXAT VCI2 - CAN			
	Next click on the Settings button and the corresponding settings for			
	the selected driver are displayed.			
Requisite options:	The tunable parameters are dependent on the driver			
	If the Options button is clicked, another dialog window with more			
	tunable parameters that are specific to the selected driver is displayed.			



NOTE

If required, any components that were not installed in the initial installation may be installed at a later date by simply repeating the installation procedure and selecting the desired components to be installed.

For further information on the exact settings, please refer to page 10.

Communication option "Start communication automatically upon loading the plant configuration"

i

NOTE

Placing a check mark in the box next to the text enables this option. If this has been enabled, LeoPC1 will attempt to establish communication with the control unit immediately after the plant configuration has been loaded. If this option is disabled communication with the control unit must be started manually.

Remote control and Displays	Select a mode from the list below:
Mode	activated
or	deactivate while parameterizing/loading language
or	not activated
Figure 2.35	deactivated while parameterizing/loading language 💌
Remote control and Displays	activated deactivated while parameterizing/loading language not activated
To define the alarm directory	Select "Devices" from the Command menu, "Settings" from the drop
Editing how	uown menu, the General Options tab, and click off.
Editing box:	"Path for alarm files:": text box and enter the desired directory
or	Click on the icon for "Path for alarm files:" and click on the approx

Click on the icon for "Path for alarm files." and click on the appropriate file folders in the "Select Path" dialog window.



NOTE

Faults that occur on your plant are logged in files that are stored in the directory specified here. This directory is always relative to the position of the corresponding plant configuration file (CFG file) and not relative to the position of the application file "Main.exe". This means that if the CFG file is not stored in the main directory, the path must be completely specified for the directory "Alarms\" or a corresponding directory must be created in the directory in which the CFG file is located.

Ensure that the new pathway ends with "\" or it may not function correctly.

To define the alarm help fileSelect "Devices" from the Command menu, "Settings…" from the drop
down menu, the "General Options" tab, and click on:
"Help file for alarms:": and enter data path
Click on the _____ icon for "Help file for alarms:" and click on the appropri-
ate file folders in the "Open" dialog window.Service Configuration

NOTE

The settings on this tab page should only be changed by experienced users or by your support team. Under certain circumstances the application will no longer process all data if the wrong parameters are entered here. Any changes made to this tab page do not become active until the application has been restarted or the plant configuration has been reloaded.

Settings...

To open device settings	Select "Devices" from the Command menu, "Settings" from the drop down menu (the "Settings to parameterize system" dialog window will open)		
	and click on:		
Figure 2.36	Devices View System	?	
Open Device Settings	Load Language	F7	

Service Configuration tab (changes the displayed tab page)

Figure 2.37	Settings to parameterize system	×
Service Configuration	General Options Service Configuration Enable Program Modules	
	C0000	
	Size of <u>d</u> ata buffer	
	ID for the first setting for remote monitoring 900	
	Size of <u>b</u> uffer for remote monitoring 134	
	Test modus (set data with default values)	
	ID for remote control word 503	
	Break for data transfer 100 ms	
	Text within title row <a>Enter custom title here>	_
	Show name of program as title?	
	Please note: without restarting this program your changes will not be done !	
	<u>Q</u> K <u>C</u> ancel <u>Apply</u> H	lelp

To define the data buffer: Open Service Configuration tab page and click on:

- Editing boxes: "Size of the data buffer" text box (The entered value must be greater than the highest parameter-ID and greater than the "ID of the first entry for remote monitoring" plus the "Size of the data buffer for remote monitoring")
 - and "ID of the first entry for remote monitoring" (The entry is dependent on the device and must be larger than the highest parameterization ID, all higher values will be ignored).
 - and "Size of the data buffer for remote monitoring" (Entry is the number of display data words plus 1).



NOTE

Some older control units may have different default values than newer control units of the same model in the text field "Size of the buffer for remote monitoring". If an incorrect value has been entered, some or all of the monitored values will not be displayed or logged!

Option:	"Test mode" (if enabled, default values are read and saved)		
Editing boxes:	"ID for remote control word" (default is 503)		
and	"Break for data transfer" (default is 200 ms)		
To define Windows title: Editing box: Option:	Open Service setting tab page and click on: "Text within title row" (your desired title can be edited here) "Show name of program as title?" (Enables the display of the custom title by checking the block)		

Enable program modules



NOTE

The Enable Program Modules tab page specifies which modules are available for the user. Only modules with check marks in the box next to it are enabled and displayed in black text. All Modules that have been disabled are displayed in grey text.

To select application modules:	Select "Devices" fr down menu, the "E to parameterize sys	om the nable I tem" d	Command Menu, "Settings" from the drop Program Modules" tab, and click on: (the "Settings ialog window will open)
Figure 2.38	Devices View System	Tools	
Open Device Settings	Load Language	F7	
	Parameterize	F0 F3	
	Data Logging	F5	
	Remote Control	F4	
	Event Recorder	F11	
	Short Term Storage Refresh Configuration	F12	

Settings...

Enable Program Modules tab (changes the displayed tab page)

Figure 2.39	Settings to parameterize system	×
Enable Program Modules	General Options Service Configuration Enable Program Modules Alarms Data Logging Event Recorder Load Language Parametrize Remote Control Short Term Storage Standard Values	
	<u>OK</u> <u>Cancel</u> Apply Help	

to activate Insert a check mark inside the box next to the Module to deactivate Remove the check mark from the box next to the Module

View Configurations

To select view:	Select View from the Command Menu and enable the desired selection by placing a check mark next to the desired View tool:
On possible bars:	ViewTool Bar (enables quick operator control via screen buttons)
	ViewStatus Listing (supplies information to the operator)
	ViewLevels (enables fast changing between monitoring levels (i.e. power
	plant, engine, or sensors/actuators)
	View System Tools ?
	🗸 Tool Bar
	✓ Status Listing
	. 🗸 Levels
	Next View F8
	Next Engine F9
	Next Device F10
Dynamic Configuration

Using the dynamic configuration module, LeoPC1 creates the parameter lists and display levels according to the options selected.

Components of the Dynamic Configuration

The components of the dynamic configuration are not immediately recognizable. If this type of configuration is utilized, the components of the dynamic configuration are hidden in the device and relevant files (*.cfg, *.opt and *.asm) for the configuration of the plant .The components can be subdivided as follows:

Device parameters:	The corresponding values are tunable for the individual control unit and de-
	termine the parameter list for the individual application modules.
Language parameters:	The corresponding values from the system data of the application determine
	the language for the display of your measured values.
Button:	Performed via:
	DevicesRefresh Configuration
Files:	OPT files contain definitions for the dynamic configuration.
	ASM files contain options for the specific control unit and are the tool files
	required for the CFG file to communicate with the LeoPC1 program.
	CFG files contain options for the specific control unit and reflect any
	changes that have been made to parameters in the control unit.

Procedure for Dynamic Configuration



NOTE

Devices with the option of dynamic configuration usually only require this once during the setup of the control unit. Dynamic configuration will not work if the control unit is not connected to the PC/laptop running LeoPC1.



Question dialog	You are requested to	o load the new	plant configuration.	
Figure 2.42	LeoPC1		2	<u><</u>
Refresh Configuration - End	Configuration data had been refreshed. For refreshing displays and parameterizing, close current project please and load it again.			
			ОК	
and	Click the "OK" butte loaded)	on (the updatin	ig is not completed until you have re-	
	Select File New or	click on the	jcon (closes the configuration)	
and	File1 Name of the	configuration.	.cfg	
	(Re-opens and updat	tes the configu	ration)	
Figure 2.43	File Communication	Alarms Devic		
Re-load configuration	New	Ctrl+N	1	
	Open	Strg+O		
	Save	Ctrl+S		
	Save As			
	Print	Ctrl+P		
	Page View			
	Printer Settings			
	1 last opened.cfg			
	Close			

Chapter 3. Properties of LeoPC1

Depending on the type and configuration of the devices, LeoPC1 puts the components explained in detail below at your disposal.

Displays

LeoPC1 can display the current values of the connected devices. This permits for a complete overview of the status of your plant, machines, and devices.

Components of the Display

There are two primary formats to display the measured values and different statuses of your plant

- In a bit map format
- In a tabular format

In turn these formats may be configured in various ways and differ in quantity of displayed information (depending on you're the user and plant requirements).

The measured values can be displayed separately according to their significance, on plant-related, machine-related and device-related **levels:**

Power plant level:This displays the most important monitored values of the plant.Machine level:This displays the most important monitored machine values.Sensors/actors:These represent all values of monitored devices.

Within these levels it is possible to change randomly between the various displays in compliance with the user's needs and thus obtain a complete overview of your plant status. If LeoPC1 is used for configuration only, only a simple background image is displayed of the plant.

The Plant overview dialog window is composed of the following **elements** for displays in compliance with your configuration:

Text boxes:	Information and comments
Parameter boxes:	Display of monitored parameter, value, and engineering unit
Buttons:	Navigation via:
	Buttons for alarm display
	Buttons to change between different levels
Bitmap:	Makes up the background design, integrating
	title, plant component descriptors, circuit diagrams, and
	open/closed breaker positions of the generator(s) etc.
Table:	Tabular display of monitored values

Procedure for Displays

0

To load configuration: Click on:



and Select the appropriate *.cfg file from the "Open" file dialog window

NOTE

It is possible to open a *.cfg file by locating it through Windows-Explorer and double clicking on the desired file.

The control unit cannot be configured or updated unless communication between the control unit and the PC/laptop has been established.

If a *.cfg file is opened without a having an automatic connection established, the default values are displayed. If the connection is interrupted after a data transfer, the last values displayed will remain on the screen.

To set displays:	Click on:	
	DevicesSettings (The "Settings to parameterize system" dialog window will open)	
Figure 3.1	Devices View System ?	
pen Device Settings	Load Language F7	
	Settings	
	General Options tab (changes the tab page displayed)	
Figure 3.2	Settings to parameterize system	
General Options	General Options Service Configuration Enable Program Modules	
	Paths and files	
	Path for alarm files: ALARMS\	l
	Help file for alarms:	l
	Data communication	l
	Driver: IXXAT VCI2 - CAN	
	<u>S</u> ettings	
	Start communication automatically while loading the system configuration	l
	Remote control not activated	l
	Displays deactivated while parameterizing/loading language	l
	Changes will be activated immediately by submitting OK.	l
	<u>OK</u> <u>Cancel</u> <u>Apply</u> Help	

Put a check mark in the box next to "Start communication automatically upon loading the system configuration" to enable automatic communication. Displays From the Displays pull down menu select either "Deactivate while configuration/load language" or "active"

Enable all changes by clicking on

<u>o</u>k



NOTE

The next time this configuration is opened the communication is established automatically. If a connection to the control unit currently exists, all the configured values are immediately displayed.

To select view:	Click on:
	ViewNext View
	ViewNext Engine
	ViewNext Device
Figure 3.3	View System ?
Open View menu	✓ Tool Bar
	🗸 Status Listing
	✓ Levels
	Next View E8
	Next Fraire FO
	Next Engine F9
or	Pull down menu of plant level
	Pull down menu of engine level
	Pull down menu of device level (sensors/actors)
Figure 3.4	Sensors/actors 💌 Engine 1 💌 Gen. 1
Select View Levels	Level powerplant
	Engine level
and	Select the desired level
unu	
To close a configuration:	Click on:
	FileClose or click the icon (terminates your application)
	FileOpenor click the file icon and select the appropriate *.cfg file from
	the "Open" file dialog window
or	File1 **.cfg
or	File2 **.cfg
or	File3 **.cfg
	Opens the selected configuration and simultaneously closes the previously
	opened configuration file

Configuration

LeoPC1 can provide user support for the configuration of a control unit. This program permits a control unit to be set up for a new application or adapted for new requirements to an existing system within the control unit's individual parameters.



NOTE

In some cases it may be necessary to see the parameter list without displaying any configured values of a control unit. This can be accomplished by selecting "Devices" from the Command Menu and "Settings..." from the drop down menu. Click on the "Service Configuration" tab to display the tab page. Insert a check mark in the box to the right of the text "Test modus (set data with default values)". Verify any changes made to the tab page by clicking the "OK" button.

This function enables the user to configure, print, and/or save parameter lists without affecting any selected drivers or connected devices.

Do not use STD files that have been created in the Test modus to configure any control units. Some parameters will not load correctly unless the control unit is running and communicating with LeoPC1 when the change to the parameter is made.

Ensure that the "Test modus" is disabled after it is no longer required. Failure to do so will result in the user not being able to configure control units until this function is disabled.

Components of the Configuration

For online configuration LeoPC1 provides a **configuration dialog window** with the following functions:

Device to be parameterized:	Selection via the pull down menu with all corresponding devices
Relevant parameter:	Display of:
	Name (designation of the parameter)
	Value (value last read of the parameter)
and	Rights (read = 'R' and/or write = 'W')

Buttons:	Handling via:	
-----------------	---------------	--

<u>I</u> nput	(By this means you change and transfer the parameters)
<u>M</u> arked rows	(Reads one or more current values from the device)
St <u>o</u> p	(Aborts reading of values)
<u>R</u> ead all	(Reads all current values from the device)
<u>P</u> rint	(Prints out the current parameter list)
<u>S</u> ave	(Saves the current parameter list as an STD file)
Help	(Calls corresponding help file)
<u>C</u> lose	(Closes the configuration dialog)

NOTE

It is possible to parameterize multiple units by saving the control unit configuration as an STD file. If the user desires to transfer the same configuration settings to a second control unit, this is accomplished by utilizing the "Standard Values" dialog window (see "Standard Values" after page 49).

1

Procedure for Configuration

NOTE Communication between the control unit and LeoPC1 must exist for online configuration. If this connection does not exist, you will be asked whether you wish to start this connection.

To connect:	Click on:			
	CommunicationConnect or vice is made)	the icon (connection to th	ne selected de-
To open configuration:	Click on:			
Figure 3.5 Open Parameterize	DevicesConfigurationor th Devices View System ? Load Language F7 Standard Values F6 Parameterize F3 Select the desired control unit devices listed	e P icon (C	Configuration di down menu wit	alog is opened) h all available
Figure 3.6	Parametrize			×
Parameterize	Please select <u>d</u> evice:			<u>C</u> lose
	Generator 1		<u> </u>	Help
	Name	Value	Rights 🔺	Input
	MAIN MENU		в	Stop
	> Password CAN > Password DPC	0000 0000	W W	<u>Marked rows</u>
	1MEASURING			<u>R</u> ead all
	 > Rated system frequency > Rated voltage generator > Rated voltage mains > Generator voltage measuring > Generator current measuring > Mains voltage measuring 		RW RW RW RW RW	Print
	> Mains current measuring > Rated active power [kW] > Rated current 1 1TRANSFORMER		RW RW RW	<u>S</u> ave



NOTE

Before the parameters for a control unit may be changed, it may be necessary to enter a password in the Parameterize dialog window. If this is required follow the operating instructions that pertain to the device being configured.

To unlock the device To enable configuration, double click on: protection:

Parameter "password level 2" in the Parameterize dialog window (the password dialog window will open)

Figure 3.7 Enter Password

Enter A Number	×	
Password Lev	rel 2	<u>0</u> K
Mask:	0000	<u>C</u> ancel
Input:		Help
Input range:	0000 9999	



NOTE

After the password has been accepted, the user may change all parameters with write rights ("W" in the column Rights). A parameter that has only a read right ("R" in the column Rights) cannot be changed.

Parameterization: Open Parameterization and click on:

Read all (Only if all current parameters are to be read)

- or Highlight one or more parameter that should be read
- and Click Marked rows (the marked line values are read from the device) or Double click on the desired parameter (scroll in parameterization dialog
- and click Input (an input dialog window for the parameter open)

NOTE

For the input dialog window, a range of values that conform to the parameter type may be entered. The possible inputs can be found in chapter "Inputs (Configuration and Standard Values)" beginning on page 45.

In contrast to the standard values dialog, the parameters entered via the input dialog windows are transferred immediately to the device when the user confirms the input dialog with the "Ok" button. Prior to making any changes, ensure that values being transferred are the required values.

All parameters that failed to read when prompted are highlighted in blue. The user may attempt to reread these parameters by clicking on the "Marked Rows" button.

To stop:	Click on:
	Stop (Aborts reading of values)
To print:	Click on:
	Print
and	Select the desired options in the print dialog window
T	
To save:	Click on:
	Save
and	Create or update file in the "Save As" dialog window



The file name must end with ".std" and the file must have the STD format. The current settings will be saved in STD format in the file specified by the user. The STD file may be modified offline without an existing connection or for archiving as standard values that may be transferred to a control unit through the Standard Values procedure.

To disconnect:	Click on:
	CommunicationInterrupt or click on the icon (terminates the connection)

Inputs (Configuration and Standard Values)

Enter A Number Enter the numerical value for a parameter in the input range. The first line of text for the window is the parameter description. The second line is a generic screen definition for the control unit. The third line is the input field in that the user can change the value. The last line is the input range. Verify any

changes made by clicking on

Figure 3.8 Enter A Number

> Rated volta	age generator	<u></u> K
Mask:	000000	<u>C</u> ancel
Input:	000400	<u>H</u> elp
Input range:	000050V 650000V	

<u>0</u>K

Real power set value	Outgoing power	Fixed value power	Reference power
Input	E0000 to 6900	C0000 to 6900	10000 to 6900
Cosine-Phi	Capacitive/Lagging		Inductive/Leading
Input	k0.01 to 0.99	1.00	i0.01 to 0.99

Flags The first line of text is the parameter description. The input field contains up to a maximum of 16 discrete inputs, which may be enabled (E) or disabled (D). In order to change the state, check marks must be added or removed from the boxes to the left of the discrete input. Verify any changes made by



×

Connector Group The first line of text is the parameter description. Below the parameter description are four buttons that display the current status of the button. To change a status, press the desired button. The button will change the displayed status to the next value. Verify any changes by clicking on OK

Figure 3.10	Connector Group	×
Set a Connector Group	Dig.input 1-4 function (E/D)	<u> </u>
		<u>C</u> ancel
		<u>H</u> elp

Insert YES/NO Set value of the parameter on YES or NO. The first line of text is the parameter description. Below the parameter description is the option field. The option may be changed by clicking on the desired field and verified by click-ОК

	ing on	
Figure 3.11	Insert Yes/No	×
Insert Yes/No	Mains voltage monitorin	DD K
		<u>C</u> ancel
	Input 💿 Na O Yes	<u>H</u> elp

Select A Text The first line of text is the parameter description. Below the parameter description is the input field that contains a pull down menu to select the desired text. The top line is the current displayed text. The text messages listed below are the messages that may be configured to the input. Verify any

ΩК

	changes by cl	icking on <u>OK</u> .		
Figure 3.12	Insert Text			×
Select Text	Function t	erminal 6:		ОК
				Cancel
	Input	Sprinkler	•	Help
		Sprinkler		
		Release Engine External acknoledgement		

Insert A Text	The first line of te	ext is the parameter d	escription. Below the	parameter de-
	scription is the in	put field. The user m	ay define the text of a	parameter up to
	16 digits in the in	put field. Verify any	changes by clicking or	n
	<u>0</u> K			
Figure 3.13	Insert Text		J	×
Insert Text	> DI 1 text		<u>0</u> K]
			<u> </u>	
	Input	mergency Stop	<u>H</u> elp	
Input Relav	The first line of te	ext is the parameter d	escription Below the	narameter de-
F	scription is the in here. The numeric symbols listed be transmitted in thre ager functions ma	put field. The relay n c codes for the desire low. Up to three func- ee sequential words. by be found in the pro-	hanager function linking of functions are linked. Attions may be linked. The numeric codes for boduct manual that is be	is configured with the logic the links are the relay man- ing configured.
	Verify any change	es by clicking on	<u>0</u> K	
Figure 3.14 Input Relay	Input Relay			×
	Assignment 1.	relay	<u>0</u> K	J
			<u>C</u> ancel	
	Input 7	1+72	<u>H</u> elp	
e of links	OR	AND	NOT	End coding

Type of links	OR	AND	NOT	End coding
Input	+	*	-	

Logic manager The *LogicsManager* is configurable with up to two time delays, three input fields, two unary sign inputs, and two Boolean sign inputs. Verify any



Sign, unary	NOT value	Value	always "1"	always "0"
Description	The value is inverted	The value is looped 1:1	The value is inde- pendent of the ac- tual state pass over as "TRUE".	The value is inde- pendent of the ac- tual state pass over "FALSE".
Input	$\stackrel{\sim}{\sim}$		1 —	0 —

Linkage, binary	AND	NAND	OR	NOR	XOR	NXOR
Description	Logical AND	Negative Logical AND	Logical OR	Negative Logical OR	Exclusive OR	Negative Exclusive OR
Input		\triangle	\square	\triangle	\bigcirc	\Rightarrow

Standard Values

LeoPC1 permits the user to archive plant-specific parameter settings as standard value files. These files can be stored and modified offline. The user may later transfer these files to the appropriate device. This function permits the user to quickly configure multiple control units of the same design to the same configuration of a pre-existing control unit.

Components of the Standard Values

For configuration with standard values a **standard value dialog window** is available to the user with the following functions:

Devices to be parameterized:	Selection via pull down menu with all corresponding devices
Device of the open file:	Selection via pull down menu with all corresponding devices
Relevant parameters:	Display of:
	Name (designation of the parameter)
	Value (value last read of the parameter)
and	Rights (read = 'R' and/or write = 'W')
Buttons:	Handling via:
	Load (loads the desired file in STD format)
	Input (the user may change the parameters without transferring the file)
	Marked rows (transfers one or more selected values to the device)
	All rows (transfers all displayed values to the device)
	Stop (aborts transfer of values)
	Print (prints out the current parameter list)
	Save (saves the current parameter list as an STD file)
	Help (opens the Help window)
	Close (closes the standard values dialog window)

Procedure for the Standard Values



NOTE

Only one path of communication should exist with a device that is going to be parameterized with standard values. The path of communication should be initiated prior to opening the "Standard Values" dialog window if any parameters are going to be transferred. If parameter values are just going to be modified and not transferred, it is not necessary to establish communication with the control unit.

If only one control unit needs to have the parameters modified, it is better to perform these modifications online with the "Parameterization" dialog window ... (see "General Configuration" starting on page 26).

When configuring with the "Standard Values" dialog window, only load files that have been taken from identical control units. <u>Do Not</u> use empty STD files (i.e. STD files from the demo). If empty STD files are used, errors in the configuration may occur under certain circumstances.

To connect: Click on:



To open standard values: Click on: S Devices...Standard values...or the icon Devices View System ? Figure 3.16 **Open Standard Values** Load Language ... Standard Values ... F6 F3 Parameterize ... Load .. Click Select the desired *.std file from the "Open" file dialog window. and Standard Values X Figure 3.17 Standard Values Current file: <u>C</u>lose C:\Projects\Std\Generator 1.std <u>H</u>elp Device: Input Generator 1 • <u>Print</u> Value Rights ٠ Name -----MAIN MENU-----Transmit value > Random number for password 8437 R > Password CAN 0000 W > Password DPC 0000 W Marked rows 1 -----MEASURING-----All rows ΒW > Rated system frequency 50Hz > Rated voltage generator 000400V RW 000400V > Rated voltage mains RW > Generator voltage measuring 3Ph 4W RW File > Generator current measuring L1 L2 L3 RW 3Ph 4W BW > Mains voltage measuring Load > Mains current measuring Phase L1 RW • Save Transmit standard values into this device: • Generator 1



NOTE

The file name must end with ".std" and the file must have the format STD.

Select the control unit to be configured from the pull down menu at the bottom of the "Standard Values" dialog window.

NOTE

Prior to changing any parameters in a control unit, the level 2 password must be entered into the device. Follow the procedure for entering a password that applies to the individual control unit.

To unlock the device protection	Open standard values and click on:
or	Parameter "password level 2" in the list box Next click on Double click on the text line for the password (the "Input" dialog window will open)
Figure 3.18	Enter A Number
Enter Password	Password CAN <u>QK</u> Mask: 0000 Input: Help
	Input range: 0000 9999
and	Enter the correct password for the control unit
and	Click on <u>Marked rows</u> (this will transmit the password)



After the password has been accepted, all parameters with write rights ("W" in the column Rights) may be changed. A parameter that has only read rights ("R" in the column Rights) cannot be changed.

To parameterize:	Open the "Standard Values" dialog window and click on:
	Desired parameter (scroll in parameter list to the corresponding position)
	Click on Input (an input dialog window appropriate for the pa-
	rameter is opened)



NOTE

There are various input dialog windows for entering parameter values. The input dialog windows vary according to the type of parameter.

The possible inputs may be found in the "Inputs (Configuration and Standard Values)" chapter starting on page 45.

Unlike the configuration dialog window, the values modified here are not transferred immediately to the control unit. These values must be transferred separately.

If parameter cannot be written an error message is displayed.

To transfer:	Open the "Standard Values" dialog window and click on:		
	One or more lines that should be transferred to the device (to highlight mul-		
	tiple line hold the "Ctrl" button on the keyboard while highlighting the pa-		
1	rameters)		
and	<u>Marked rows</u> (Values of the marked lines are transferred to the device)		
or	All rows (All values are transferred to the device)		
To stop:	Click on:		
	Stop (Only if necessary to abort transfer of values)		
To and the			
1 o print:	Click on:		
	<u>Print</u>		
and	Select the desired options in the print dialog window		
and	Select the desired options in the print dialog window		

To save: Click on:

```
<u>S</u>ave
```

and The desired file via the "Save as" dialog window

NOTE

When saving a file, the file name must end with ".std" and the file must have the STD format. After a file has been saved in this format, it is available for modification or archiving as standard values that can be loaded and transferred at a future date. Saving the file again is only required if the values of the previously loaded file been changed.

To disconnect: Click on:

Communication...Interrupt or the kicon (terminates the connection)

(Closes the remote control dialog window)

Remote Control

LeoPC1 can provide the user with support for the control of your control unit from a remote location. This permits the user to start and stop the plant, machines, and devices or modify selected parameters right from your office or residence.

Components of the Remote Control

For control a remote control dialog window with the following functions is available:

Device to be controlled:	Selection via pull down menu with all available devices		
Remote control parameters:	Editable values:		
	Set point of active power		
	Generator Cosphi (power factor)		
Control words:	Enable/disable:		
	Acknowledgement (resets the alarm memory of the device)		
	Remote stop (stops your controlled machine)		
	Remote start (starts your controlled machine)		
Buttons:	Handling via:		
	Set (Transfers the selected commands to the device)		
	Help (Opens Help window)		
	Close		

NOTE

The Control Word "Acknowledgement" is automatically reset after a specific time period if the existing communication link does not permit the message to transmit constantly.

The Command Word "Remote Stop" has priority over "Remote Start" if there is an existing communication link to the control unit.

Procedure for the Remote Control



NOTE

If the user desires to use the remote control feature, this must be set when starting the configuration. The remote control feature must be enabled individually for each unit that will utilize this. The control unit must be configured for remote control and not controlled by another component of the system. Read the operation instructions for the control unit prior to enabling the remote control function.

To define communication:	Click on:
	DevicesSettings (Settings to parameterize system dialog is opened)
Figure 3.19	Devices View System ?
Open Device Settings	Load Language F7
	Settings
	General Options tab (changes the displayed dialog window)
Figure 3.20	Settings to parameterize system
General Options	General Options Service Configuration Enable Program Modules
	Paths and files
	Path for alarm files: ALARMS\
	Hein file for alarms:
	Data communication
	Driver: IXXAT VCI2 - CAN
	Settings
	Start communication automatically while loading the system configuration
	Remote control
	Displays deactivated while parameterizing/loading language
	Changes will be activated immediately by submitting OK.
	<u>OK</u> <u>Cancel</u> <u>Apply</u> Help
Remote control	Select "activated" (standard)
or	"Deactivate while parameterizing/load language"
	Verify changes by clicking on <u>QK</u>
To connect:	Click on
	11
	CommunicationConnect or the u icon (the connection to the selected
	device is created)

To open remote control:	Click on:	
Figure 3.21 Open Remote Control	DevicesRemote control or the F Devices View System Load Language F7 Remote Control F4 Event Recorder F11	
To select:	Open remote control and click on: The control unit to be controlled (pull down menu with all available devices)	
Figure 3.22 Remote Control	Remote Control Please select the device that has to be remote controlled: Generator 1 Remote control data Sgtpoint of active power: C0025 kW I6900kW Generator cosphi: 1.00 k0.71 Control word Acknowledgment Remote stop Remote start	
To control: Desired editing box: and/or and Desired option/s: and/or and/or and	Open remote control and click on: Active power set point (set process and kW level) Generator Cosphi (set power factor) Input the requisite value Acknowledgement (resets the alarm bits in the device) Remote stop (overrides remote start if it is selected simultaneously) Remote start Click	
To disconnect:	Click on:	
	CommunicationInterrupt or the icon (terminates the connection)	

Data Logging

LeoPC1 has the capability to perform data logging of selected parameters of the user's plant for the purpose of control.

Device to be controlled: Measured values to be logged: Selected values: Logging parameters: Display individual line: Display several lines:	Selection via pull down menu with all available devices Selection via pull down menu with the specific measured values Display on data diagram with time and value axis Display of sampling rate and logging time period Option that displays only the selected measured value Option that displays all measured values defined in a maximum of 8 buttons	
Parameter dialog:	with the following options: Logging time period in minutes Sampling rate in seconds Display of the storage space requirement to be expected	
Scaling dialog:	With the following options: Logging time period axis X with selection facility of: Complete logging time period Individual setting (time from to) Measured value, axis Y, with facility for selecting: Complete value range Individual setting (measured value from to)	
Buttons:	Handling via: <pre> Kempty> (Selected values for 8 parameters that can be individually for- matted and scaled) (Allows the insertion, removal and setting of the selected measured val- ues) Start (Starts the desired logging) Stop (Stops the desired logging) Load (Loads the desired file in LLO format onto the display) Unload (Closes the current file in LLO format on the display) Print (Prints out the current logging diagram) Save (Saves the current logging as an LLO file) Help (Opens the Help window) Close the data logging dialog) </pre>	

Procedure for Data Logging

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It is possible to set data logging when the configuration is started.

To define data logging:	Click on:	
Figure 3.23 Open System Settings	System ? User log off User Management System Settings Settings tab (changes the displayed tab page)	
Figure 3.24 System Settings	Settings X	
	Language: English	
	☑ Start data logging automatically while loading your system.	
	Save data logging automatically while closing your system.	
	in file: C:\Projects\DL\Logging.llo	
	Settings for export data logging files	
	✓ Output <u>h</u> eading line ?	
	Seperater ;	
	<u>O</u> K <u>Cancel</u> Apply Help	
	Start data logging automatically while loading your system.	
activate	Save data logging automatically while closing your system.	
deactivate	Remove the check mark	
	Click the icon to right of the "in file:" text box and create or select the	
	file to store the data in from the "Save as" dialog window.	
NOTE		
File name must end in ".llo" and the file must have the format LLO.		
To log:	Click on:	
	Communicationconnect or the icon (the connection to the selected device is established)	



To load: Click on:



and Select the file to be loaded from the "Open" file dialog window

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NOTE

Set the tick desired by you to activate the option.

To select:	Open data logging and click on: Desired device (pull down menu with all available devices) Desired measured value (pull down menu with all corresponding measured values)
Desired options:	Display single line (the selected measure value is displayed)
or	Display several lines (the selected and inserted measured values are dis-
and	played with their individually definable scaling and formatting) Click on (allows you an assignment of the selected measured
	value) Click the button (select the appropriate action from the drop down menu)
	Append: adds the selected parameter to be monitored to the selected button.
	Delete: removes the selected parameter from the selected button.
or	Properties opens the "Line Setting Definition" dialog window
and	If necessary assign its scaling individually by clicking on Scaling

To log:	Open data logging and click on:				
	Parameter (The "Dat	a logging –p	arameter" d	ialog window will c	open)
Figure 3.27	Data Logging - Param	ieter			
Data Logging - Parameter					
	Logging time period:	120	Minutes	<u> </u>	
	Sampling	5	seconds	<u>C</u> ancel	
	Expected memory size	to save as a fi	le:	<u>H</u> elp	
	140 kB				
Desired editing box:	Sampling rate (enter va	lue between	2 and 120 se	econds)	
and/or	Logging time period (v	alue betweer	1 and 32,70	67 minutes possible)
	OK (Parame	eter dialog is	closed)		

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Prior to starting data logging ensure that there is enough storage space for the file that is created. When smaller sampling rates for longer periods of time are utilized, the larger the file size becomes. If adequate storage space is not available for the data-logging file, the data logging will not occur. Files of several megabytes can be produced quickly with long periods of data logging. The file for the data logging session is create prior to the session starting, preventing the hard drive space being utilized for other applications.

	Scaling (A dialog window for changing the scaling range is opened)	
Figure 3.28	Data Logging - Scaling	
Data Logging - Scaling	Period of time for data logging (X-axis) □K © Complete logging time period □L © Individual settings from: from: 14.07.04 15:53:14 tt.mm.jjjj to: 14.07.04 17:53:14 tt.mm.jjjj Bange: 14.07.2004 15:53:14 tt.mm.jjjj b: 14.07.2004 15:53:14 tt.mm.jjjj b: 14.07.2004 15:53:14 tt.mm.jjjj b: 0 Display the last 5 minutes. Measuring value (Y-axis) © Complete value range Mgasuring value -10 V tg: 400 V V 10 V	
Select desired options:	Complete logging time period (according to the specified time)	
or	Individual setting	
and	Enter time range from to	
Select desired options:	Complete value range (according to the specified parameters)	
or	Individual setting	
and	Enter measured value range from to	
	Verify changes by clicking on $\Box K$ (scaling dialog is closed)	



A change in the scaling results in an enlargement of the extracted data that is retained after the logging window is closed. If the option "Display several lines" is selected, the individual lines may be defined and activated by selecting the desired parameter button and editing the scaling for that parameter.

Click	S <u>t</u> art	(the selected recording will be started)
CIICK.		(the selected recording will be started)

To zoom: Place the cursor at the start of the area that is to be examined and highlight the desired area by pressing and holding the left mouse key. Release the mouse key when the desired area is completely highlighted. It is possible to perform this process multiple times. Reset the zoom by clicking the right-hand mouse key (if necessary, by clicking it several times). The user may zoom out by pressing and releasing the right mouse button. This may be performed multiple times or until the original scale is displayed.

To stop: Click on: Stop (Only if it is necessary to terminate the procedure prematurely)

To print: Click on:

<u>P</u>rint

And Select the desired options in the print dialog

To save: Click on:

<u>S</u>ave

And Select via the Save as dialog



NOTE

File name must end in ".llo" and the file must have the format LLO.

To unload: Click on:

Unload (Only if you would like to close the file currently loaded)

Disconnect: Click on:

Communication...disconnect or the kick icon (terminates the connection)

Short-term Storage

LeoPC1 can log specific criteria of selected events from the available control units. The monitored parameters for this selective logging are displayed as a guide value.

Components of the Short-term Storage

The LeoPC1 provides a Short-term storage dialog for logging appropriate defined events or limiting values. Functions are as follows:

General dialog: Buttons:	with the following options: Current settings Selected device: Activation by: <selected alarm="" parameter="" value=""> Start Short-term storage automatically while loading system Settings (Opens the Settings dialog) Start (Starts the desired monitoring) Stop</selected>
Protocol dialog:	with the following options: Events that occurred No., Date, File, Start, End, Event Delete (Deletes all events from the display)
Buttons:	Handling via: <u>Apply</u> (Confirms changes without closing the dialog window) <u>Help</u> (Opens Help window) <u>Cancel</u> (Closes the Short-term storage dialog window) <u>OK</u> (Confirms changes and closes the dialog window)
Settings dialog:	 Tunable: Device (pull down menu with all available devices) Value for activating Short-term storage Alarm (pull down menu with all possible alarms) Exceeding a limit value (pull down menu for parameter, box for limit value) Edited value (selection of the Displayed ID, the operator, box for event value) Recording parameter At issue time in seconds Saving interval in seconds

- Hold-back time in seconds
- Follow-up time in seconds

File name (file name the event is saved as in the DL directory) Display of the expected storage space requirement per event

Procedure for Short-term Storage



NOTE

Only one event can be monitored at a time. If the monitored fault condition occurs during the follow-up time, the event is not logged. The short-term storage is still processing the data from the previous fault occurrence and is not reset for monitoring.

The parameter settings described in the following text are dependent upon the configured settings and the configuration of the plant to be monitored. If a low save interval setting is configured and a large data base must be processed or a low Hold-back time is configured, the result may be that the time interval that is save is larger than the time interval that was configured.

Γο open short-time storage:	Click on:
Figure 3.29 Open Short-term Storage	DevicesShort-term storageor the window will open) K Devices View System Load Language F7 Short Term Storage F12
Figure 3.30	Short Term Storage
Short-term Storage	General Protocol Current settings: Device: Activated by:
	QK Cancel Apply Help

To set:	Open short-term storage and click on: General tab page (changes the dialog level)		
Figure 3.31	Settings		
Short-term Storage - Settings	Definition of source for activating short term storage	<u>0</u> K	
	Device: Generator 1	<u>C</u> ancel	
	Value for activating short term storage	<u>H</u> elp	
	Error / Alarm User defined 1		
	C Exceeding a limit value		
	C Edited ⊻alue		
	Recording parameters		
	At issue time: 3 seconds		
	Saving interval: 1 seconds		
	Hold-back time: 300 seconds		
	Follow-up time: 400 seconds		
	Please chose file name for saving results of this short term storage when the choosen coasting time is over:		
	Eile name: Gen1_%d-%m-%Y %H-%M.llo		
	Expected storage space requirement per 68 kB		
Desired event source:	Desired device (pull down menu with all available devices)		
Desired event:	Activation of:		
Error/Alarm	Enable by clicking on text (activates as soon as the defined alarm has oc-		
	curred)		
and	Selection of the error/alarm message of the pull down list with a	ll defined	

If an event that is controlled by an alarm message, only select the activating message.

events.

Exceeding a limit value	Enable by clicking on text (activates as soon as a limit value has been ex-
	ceeded)
and	Selection of the desired measured parameter from the pull down list
and	Input of the desired upper limit value

NOTE

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If you wish to utilize the option "Exceeding a limit value", select the parameter to be measured and enter the corresponding limit value.

> Edited value Activates as soon as the condition is fulfilled

- and
 - Selection of the desired display ID from pull down menu (list of protocol)
 - and Selection of the appropriate operator

NOTE

The option "Edited value" offers the user more complex configurations. This does also require detailed knowledge of operands. The input of the value occurs unformatted (i.e. a battery voltage of 24.8 volts (formatted) is input as 248 (unformatted)).

Operand	AND	Less than	Less equal	Greater than	Greater	Equal
					equal	
Description	Logic AND, for interpreta- tion binary values	Less than the specified value	Less than or equal tithe specified value	Greater than the specified value	Greater than or equal tithe specified value	Equal to the specified value
Input	AND	<	<=	>	>=	=

Desired parameters: Input of:

At issue timeMinimum time for which the event must occur to activate monitoringSaving intervalMinimum time that should lie between two data samplingsHold-back timeTime that is logged before and after the event occurs to show system status
prior to and during the fault condition

Follow-up time Time required for the data logging to process the collected data

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The Holdback time and the Follow-up time added together make up the entire logging time period.

and File name (designation of the file in which the event period is saved) Example Event-on_2001-07-13_at_12-12_hrs.llo

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L)
T	Γ

NOTE

NOTE

When assigning the file name, it is possible to use a time stamp:

Permitted formatting	Year	Month	Day	Weekday / Week	Hours / Minutes / Seconds
Input	%Y / %y	%m / %b / %B	%d / %a / %A	%w / %W	%H / %M / %S
Format (example)	2004 / 04	06 / Jun / June	30 / Mo / Monday	3 / 27	10 / 55 / 45

To monitor: Open short-term storage and click on:

Start (in the status line "STS" appears)

Start Short-term storage automatically upon loading the configuration

and If a defined event occurs, logging is activated

To stop: Open short-time storage and click on:

and Monitoring of the event is terminated



NOTE

It is possible to graphically display the generated files via the data logging module and, if required, select and export the measured values as described there.

To monitor:	Open short-time storage and click on: Protocol tab (changes the displayed tab page)
Figure 3.32	Short Term Storage
Short-term Storage - Protocol	General Protocol
	Events that occurred No. Date File Start End Event
	<u>D</u> elete
	<u>QK</u> <u>Cancel</u> <u>Apply</u> <u>Help</u>
and	The events that have already occurred are displayed with:
	No., Date, File, Start, End, Event

The "Events that occurred" list does not automatically update. To update the list the dialog window must be closed and re-opened. When a new event occurs the previous events are deleted from the display.

(Deletes all displayed events from the dialog window)

Alarm Management

LeoPC1 can log and display all events and alarms that occur in the connected devices.

<u>D</u>elete

Components of the Alarm Management

The following components are available for alarm management:

Alarm Management Dialog with the Following Functions:

Desired alarm file:	Selection via scroll menu of the possible devices		
Buttons:	Handling via:		
Corresponding alarm list:	Display of alarm time (Time until)		
	<u>H</u> elp	(Opens Help window)	
	Entry (For manual entries in the alarm list)		
	P <u>r</u> int	(Currently not functional)	
	<u>C</u> lose	(Closes the alarm management dialog window)	

Current Alarm Dialogs with the Following Functions:

Current alarms: Display of the current or device specific alarms Buttons: Handling via:

Handling via: <u>Help</u> (Opens help window if available)

<u>C</u>lose

(Closes the current alarm dialog window)

Procedure for Alarm Management

NOTE If configured as follows, a new file is created for each day. The file name is assigned as the date. Communication to the control unit must exist for these files to be created.

To define system settings:	Click on: DevicesSettings (Settings to parameterize system dialog window will open)
Figure 3.33 Open Device Settings	Devices View System ? Load Language F7 Settings
Figure 3.34 General Options	Settings to parameterize system X General Options Service Configuration Enable Program Modules Paths and files
Editing box: or	Click on the text box for "Path for alarm files": and enter directory Click on the icon and select from the "Select Path" directory dialog window ("ALARMS\" is the default)



NOTE

This directory is always relative to where the corresponding plant configuration file (CFG file) is stored and is not relative to where the applications file "Main.exe" is located. If the CFG file is not stored in the main directory, the user must specify the path completely for the directory "ALARMS\" or in the directory where the CFG file is located an alarms directory must be created.

Ensure that the pathway input into the settings ends with '\'.

Editing box: 'Help file for alarms': and enter file path

or Click on the _____ icon and select file path from the "Open" file dialog window

Managing Alarms

To open alarm management: Click on:

Figure 3.35 Open Alarm Management Alarms...Management... ("Alarm Management" dialog window will open) Alarms Devices View Show Current ... Management ...

Figure 3 36	Alarm Managemen	t				
Figure 3.36 Alarm Management	Alarm Managemen Error files 07.alm 13.alm 14.alm 22.alm 23.alm 24.alm 25.alm	t Errors User defined 1 GCB fail to open User defined 1 GCB fail to open User defined 1 GCB fail to open		Time 14:50:35 14:50:35 15:13:02 15:13:02 15:16:24 15:16:24	Until	<u>C</u> lose <u>H</u> elp <u>Entry</u> Pgint
To select:	Open alarm 1 Desired file i	management and click in the scroll menu alar	on: m files			×
To print:	Open alarm 1 Print	management and click	on:			
and	Select the de	sired options in the pri	int dialog winde	зw		
To comment: Figure 3.37	Open alarm r Entry Manual Inp	management and click (Manual input in the a ut Into Error List	on: Iarm list dialog	; windo	ow will o	open)
Manual Input Into Error List	Kenter your	notes here> ithK	Cancel		<u>H</u> elp	

and Manually enter the desired text (line break with Ctrl +Enter)

Show Current Alarms



Loading Languages

LeoPC1 can transfer to connected devices a different language. The corresponding operating instructions provide you with Information about the facilities of your devices. The following instructions provide the procedures for facilitating this function.

Components of Loading Languages

LeoPC1 provides a **Load language dialog window** for transferring a language to a control unit with the following functions:

Device to be controlled: Relevant parameters:	Selection via pull down menu with the available devices Display of:				
	INFO lines (displays comment lines) xxxx lines (xxxx stands for the number	code of the device parameters)			
Texts to be transferred:	Selection options for: All texts (marks all texts for transfer) Transfer language (user specified lines	are transferred)			
Buttons:	Handling via:				
	(Closes the load	language dialog)			
	<u>Help</u> (Calls correspon	ding Help)			
	Load LNG-file (Opens the desired	red language file)			
	Print (Prints out the lo	aded language list)			
	Stop (Stops the transfer, if required)				
	<u>Iransfer language</u> (Transfers your selection to the device)				
	Load Language X				
	Please select <u>d</u> evice to transmit language texts to:	Close			
	Generator 1 - 8440_1330_NEW_1	Help			
	Language texts: INFO 'Definitionsfile flr Fremdsprachenparametrien	ungi			
	INFO Leonhard Reglerbaul	<u>Print</u>			
	INFO 'BEGINII INFO 'INFO Hier stehen Buchstaben für UO-Texte INFO 'INFO es wird jeweils nur der erste Buchstal 0000 'EEEEEEEEEEEE 0001 'DDDDDDDDDDDDDDD 0002 'YYYYYYYYYY 0003 'NNNNNNNNNNNNNN 0004 ''''''''''''''''''''''''''''''''''	be verwendet			
	Which texts have to be transferred ?				
	All texts Texts from 0 to 0				

Procedure for Load Language

NOTE To transfer languages to your device a connection to your plant must exist. Please ensure that no other device is connected at the same time.

To connect:	Click on:
	CommunicationConnector the icon (connection to the selected device will be established)
To switch clear the device:	Click on:
	DevicesConfiguration or the P icon (the "Parameterization" dialog window is opened)
Figure 3.40	Devices View System ?
Open Parameterize	Load Language F7
	Standard Values F6
	Highlight parameter "pageword level 2" in the list her
	Input
or	Double click on parameter "password level 2" (input dialog window will
	open)
Figure 3.41	Enter A Number
Enter Password	Code Level 2 <u>DK</u>
	<u>Cancel</u>
	Mask. 0000 Help
	Input:
	Input range: 0000 9999
and	Enter the password.
	Verify the password by clicking on \underline{QK} .
NOTE	

After the password has been accepted, the language can be loaded into the control unit. Refer to the product manual prior to attempting to transfer the language texts to ensure that all settings are correct.



NOTE

The file name must end with ".Ing" and the file must have the LNG format.

Figure 3.43	Load Language	×
Load Language	Please select device to transmit language texts to:	<u>C</u> lose
	Generator 1	<u>H</u> elp
	Language t <u>e</u> xts: 0013 'Configure '	Load LNG- <u>f</u> ile
	0014 'measuring øøøøøø 0015 'Generator freq.	Print
	0016 'f set 00.0Hz 0017 'Rated system other the system	
	0018 trequency 00.0Hz 0019 'Gen. volk transf.	
	0020 secondary 000V 0021 'Gen.volt.transf. 0022 'primaru 00 0000V/	Stop
	0023 Bus volt transf. 0024 secondary 000V	<u>T</u> ransfer language
	Which texts have to be transferred ?	
	C Te <u>x</u> ts from 0 to 0	

Select the desired device (pull down menu with all available devices) The suitable language lines are displayed on the scroll menu

 To transfer:
 Click on:

 texts to be transferred
 All texts (all language texts are selected)

 or
 Texts from ... to ... (enter code number range)

 Transfer language
 Texts is the last is the selected of the selected of

(Your desired selection is transferred)



To stop:	Click on: Stop (Please only if it is necessary to terminate the procedure prematurely)					
To print:	Click on:					
-	Print					
and	Select the desired options in the print dialog					
	OK (language texts are printed out)					
To disconnect:	Click on:					
10 41500111000						
	CommunicationInterrupt or the icon (terminates the connection)					

Event Recorder

LeoPC1 can read the event recorder from the available devices. If this function is integrated, the appropriately defined events can be called up and printed out.

Components of the Event Recorder

LeoPC1 makes available to the user the reading of events or errors an **event recorder dialog window** with the following functions:

Device: Read date: Relevant parameters:	Selection via the pull down menu with the possible devices All or already read events as of the date Display of: Date on which read (only for 'Date read: All displayed) Event/error number, date, description, value (if defined)					
Buttons:	Handling via:					
	<u>C</u> lose	(Closes the event memory dialog window)				
	<u>H</u> elp	(Opens Help window)				
	<u>P</u> rint	(Prints out the read event lists)				
	<u>D</u> elete	(Deletes all previously read events)				
	<u>R</u> ead	(Starts reading of the event from the device)				
	<u>U</u> ndo	(Resets the event memory, if this function is defined)				

Procedure for the Event Recorder





Figure 3.45	Event Recorder					×
Event Recorder	De <u>v</u> ici	Generator	1		✓ <u>C</u> lose	
	D <u>a</u> te read:	All			<u> H</u> elp	
	Has been No	. Date	Description	Value	J	
					<u>D</u> elete	
					<u>P</u> rint	
					Event Recorder	
	1					

Open event recorder and click on pull down menu of: Device: (device desired to be read)

and/or Date read: (date of event desired to be read) and Selection of the list of all events already read.

Read events:

Open event recorder and click on:

Delete (If you want to delete the displayed earlier read values) <u>R</u>ead (The process is started)

Wait until the list is displayed or a prompt opens with instructions and

NOTE

The read out of the event recorder can take some time depending on the device and the selected connection.

The displayed events can be filtered by using "Read Date" as long as the events have been read previously and not deleted.

> To print: Open event recorder and click on: Print Select the desired options in the print dialog window and <u>o</u>k (Event list is printed out) To disconnect: Open event recorder and click on: Communication...Interrupt or the icon (terminates the connection)
Chapter 4. Communication and Connection

LeoPC1 can communicate with other software and hardware. It has to be differentiated between the following **communication** types:

DevicesHardware that is compatible to the LeoPC1.ApplicationsSoftware compatible to CSV format such as EXCEL or ACCESS

Various drivers and a data export are available to the user for these communications and are explained in further detail below.

General Information

Hardware and software interfaces are at the center of the data communication. Correct connection, settings, and operator control are required to ensure that the communication functions correctly. Take the following information into consideration where it relates to your requirements. If there are any questions or problems, refer to the supplied documentation or contact the manufacturer of the product (e.g. modem, CAN card, cables, etc.).

Communication with Devices

LeoPC1 supplies at your disposal the drivers listed below.

Drivers for Serial Interfaces

Direct Interface

The **direct** driver of LeoPC1 provides permits the user to directly configure the control unit through a serial connection to the computer and an RJ45 connection on the control unit. The RS-232 standard for communications is utilized with this function. The device will dictate the number of functions that may be performed through this method of communication.

Gateway RS-232 Interface

LeoPC1 provides the user with the ability to utilize the **Gateway RS-232** driver. This permits the user to configure the control unit with the RS-232 standard without using an RJ45 connection. This does require the user to drive a Gateway RS-232 in the system. This method of communication assumes that all devices in the system are communicating via a CAN bus. This method of interfacing permits the user to utilize most of the properties of LeoPC1.

Modem Interface

LeoPC1 provides the user with the ability to utilize a **modem** driver. This permits the user to configure the control units via an analog modem through the RS-232 standard without using an RJ45 connection. This does require the user to drive an analog modem in the system. This method of communication assumes that all devices in the system are communicating via a CAN bus. This method of interfacing permits the user to utilize most of the properties of LeoPC1.

Components of the Drivers for Serial Interfaces

Direct Interface



Figure 4.1 Direct interface

Gateway RS-232 interface



Figure 4.2 Gateway RS-232 interface

Modem Interface



Figure 4.3 Modem interface

NOTE

These wiring diagrams are only examples. Depending on the devices, other connections may be required. Refer to the manual for the specific requirements of your device.

Procedure for Serial Drivers

\mathbf{i}

NOTE

Before the drivers can be utilized, the hardware configuration of the control units must conform to the relevant circuit diagram or according to the unit documentation. Furthermore, you should check the software configuration with the aid of the steps described and, if necessary, adapt it to suit your requirements. In addition to the hardware requirements.

If the required driver is not installed on the computer to be utilized, the LeoPC1 installation program must be re-initiated and the required drivers installed. If only the demo version of LeoPC1 is available, contact your support team for assistance with obtaining the required drivers.

To set driver:	Click on:	
	DevicesSettings (The	e "Settings to parameterize system" dialog window
	will open)	
Figure 4.4	Devices View System	?
Open Device Settings	Load Language	F7
	Settings	
	General settings tab (char	nges the displayed tab page)
Figure 4.5	Settings to parameterize sy	stem 🔀
General Options	General Options Service Con	figuration Enable Program Modules
	- Paths and files	i
	Path for alarm files:	ALARMS\
	Halp file for plarmer	
	<u>m</u> eip nie for alanns.	
	Data communication	
	<u>D</u> river:	Direct
		Demo Direct
		Gateway - RS232
	Start communication au	Modem
	<u>R</u> emote control	not activated
	<u>D</u> isplays	deactivated while parameterizing/loading language 💌
	Changes will be activated imm	ediately by submitting UK.
		QK Cancel Apply Help

Select the desired driver (pull down menu with all installed drivers)

Settings... (Settings for *driver name* dialog window will open)

Figure 4.6	Settings for Direc	t Parameterization	X
Settings for Serial Drivers	Port	СОМ1	<u>0</u> K
	<u>B</u> aud	9600 💌	<u>C</u> ancel
	Parity	None	
	<u>D</u> ata Bits	8	Op <u>t</u> ions
	<u>S</u> top Bits	1	
Possible parameters	Port (please alloc	eate your corresponding COM port)	
Port	Select COM1. CO	OM2 or according to PC configuration	n
Baud	Set the permissible transfer speed in accordance with the specifications of the hardware being utilized		
Parity	Set "None" for as	synchronous transfer	

- Parity Set "None" for asynchronous transfer Data Bits Set "8" for asynchronous transfer
- Stop Bits Set "1" for asynchronous transfer

Information about COM port assignment can be obtained via:

- Start...Settings... Control Panel...System and corresponding selection of the options.

Information about the permissible baud rate can be obtained from the device's documentation. For example, the Gateway operates at 9,600 baud. If any problems occur, the selected driver can still be indi-

vidually configured by clicking on "Options ... " and adapted to the plant.

Most configuration files are have default values for the communication methods that do not required the user to modify these parameters. Only modem connections may require that the user to modify the settings according to the individual system conditions.

Depending on the driver, the user can modify the following settings in this dialog window:

Computer-related settings

Guide values: The settings specified here are guideline values that should be adapted to special situations as necessary. The values found in the parenthesis may be used for many units and are safer for use when doubt exists for what value should be entered.

Description	Direct	Gateway RS- 232	Modem
Number of repetitions to send a command	3 (5)	3 (5)	0 (10)
Timeout after writing a command	0 (50)	0 (100)	500
Delay between writing a command	10 (150)	10 (150)	-
Timeout after reading an incorrect answer (CAN error)	0	0 (500)	0 (1000)
Number of repetitions to read the answer	3 (5)	3 (5)	3 (10)
Timeout for reading the answer	300 (500)	300 (500)	300 (700)
Timeout if no answer was received	100	200	200 (500)

Table 4.1 Driver settings - Serial

Flow chart: This flow chart shows you the steps LeoPC1 take when attempting to establish communication with a device. This chart can be helpful determining what values may need to be adapted to your individual requirements.



Figure 4.7 Driver Timeouts Handling

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Description of the flow chart:

- 1. When a command is written/sent, the time for "timeout after writing a command" and "timeout for reading the answer" is started. If a valid answer is received before the time expires, the next command starts or the procedure ends.
- 2. If an invalid answer is received, the "timeout after reading an invalid answer" is started. If this time expires without receiving a valid answer, the "number of repetitions while reading the answer" is activated and begins its cycle at "timeout for reading the answer".
- 3. If a valid answer is not received see step #6.
- 4. If no answer is received, the time for "timeout if no answer has been received" is started. If this time expires without receiving an answer, the "number of repetitions while reading the answer" is activated and begins its cycle at "timeout for reading the answer".
- 5. If an answer is not received see step #6.
- 6. If the "number of repetitions while reading the answer" has elapsed without a valid answer being received, the "number of repetitions for send command" is initiated and the procedure begins again at step #1.
- 7. If the "number of repetitions for send command" is run through without a valid answer, the procedure is aborted.

Plant-related settings

Modem Strings Description			
Initializing	Attention command	ATH (external)	
		ATH&F0 (internal)	
Connect (P/D#)	Attention command	ATDP (pulse dialing process)	
		ATDT (tone dialing process)	
		ATX1DT or P (internal)	
Disconnect	Attention command	+++~~~ ATH ^M	
Handicap for telephone number Enter here your standard		nnection (if dialing via an outside	
	line, enter '0W' as prefix)		
Allow user to change telephone number?	Allows you to input telephone numbers other than the stan		
	dard connection		
ID for connection	Attention command	CONNECT	
	•		

Timeouts		
Initialization	Timeout	At least '40' seconds
Dialing process	Timeout	At least '40' seconds

Table 4.2 Driver settings - Modem

NOTE

If you would like to establish a connection to a foreign country, it is recommended that each timeout be increased to 60 seconds or more so that the connection can be established.

If problems still occur with the connection, please refer to the operating instructions for the modem or contact its manufacturer.

Figure 4.8	Settings for Modem		×
l iguie 4.0	Computer referring settings		
Settings for Modem	Number of repetitions to send a command	0	<u>K</u>
	Timeout after writing a command	500	<u><u> </u></u>
	Timeout after reading an incorrect answer (C4	AN-Error)	
	Number of repetitions to read the answer	3	
	⊥imeout for reading the answer	300	
	Timeout, if <u>n</u> o answer was received	200	
	Remote control does not wait for an answer		
	Remote control: timeout after sending a m	essage 0	
	Extended standard protocol	▼	
	System referring settings		
	Modem-strings	Timeouts	
	Initializing ATH	Initializing 60	s
	Connect (P/D#)	Dialing 60	s
	Disconnect +++~~~	~~~ATH	
	Handicap for telephone number		
	Allow user to change the telephone numb	er? 🔽	
	ID for connection	IECT	



A connection to the device or devices must exist in order to use the drivers for communication. The exception to this is the demo driver. The demo driver is designed to demonstrate within certain limits the properties of LeoPC1 with requiring a connection to a control device.

When the configuration buttons are clicked on, LeoPC1 will prompt the user to initiate communication with the control unit if communications have not already been established. Communications can be specified to start automatically when the plant configuration loaded. The procedures for this are shown in the following text.



NOTE

The status for communication is displayed on the level bar by the appearance of the following icons:



A connection does not exist.

A connection exists (display data are received).

Display data is not being received or the communication is not correct.

To set auto-connection: Click on:

Devices...Settings... (The "Settings to parameterize system" dialog window will open)

Figure 4.9 Open Device Settings



General settings tab page (changes the displayed dialog window)

Figure 4.10	Settings to parameterize	system 🔀
General Options	General Options Service Cor	ifiguration Enable Program Modules
	Paths and files	
	Path for alarm files:	ALARMS\
	Help file for alarms:	
	Data communication	
	Driver:	IXXAT VCI3 - CAN
		Settings
	Start communication au	Itomatically while loading the system configuration
	Remote control	not activated
	Displays	deactivated while parameterizing/loading language
	Changes will be activated im	nediately by submitting OK.

Place a check mark in the box to the left of "Start communication automatically while loading system configuration"

NOTE

1

1

If this option is selected, LeoPC1 will attempt to establish a connection with the control unit immediately after the plant configuration is loaded. If this option is not selected, the user must start the communication.

To connect:	Click on:
	CommunicationConnect or the icon (starts the connection to the device)
To disconnect:	To open event recorder and click on:
	CommunicationInterrupt or the kicon (terminates the connection)

NOTE

Take note of the communication parameters required or desired by the individual plant. Prior to terminating the connection ensure whether or not the connection is to be used for remote configuration or control.

Drivers for Network Cards



NOTE

LeoPC1 currently supports IXXAT products with VCI driver version 1.17 up to 3.5.1. For example:

- iPC-I 320, iPC-I 165 (ISA-PC cards)
- iPC-I 320 PCI, iPC-I 165 PCI (PCI-PC cards)
- tinCAN (PCMCIA-Interface, full support only with 'IXXAT VCI2 CAN' driver or higher)
- USB-to-CAN compact Interface (support only with 'IXXAT VCI2 CAN' driver or higher)

Not all CAN-interfaces are supported by all operation systems where LeoPC1 can be installed. It is not possible to use more than one IXXAT driver version at a time. If an IXXAT driver version earlier than 3.5.1 is installed on the PC/laptop, the user will be prompted to completely delete this file. If VCI 1.xx has never been installed or after the files have been deleted, driver version VCI 2.xx can be installed by using the LeoPC1 software installation utility.

CAN Bus Interface

By means of the CAN bus driver LeoPC1 provides the user the ability to connect the control units via the CAN bus to a PC/laptop, provided that the PC is compatible with one of the listed CAN cards. This interface permits the user's PC/laptop to be automatically connected to the plant, machines, and devices. The user can set parameters, control remotely, display, and load languages if necessary.

Components of the Network Card Drivers

You will find the circuit diagrams for the individual network card drivers here:

CAN Bus Interface



Figure 4.11 CAN bus interface

Procedure for Network Card Drivers



NOTE

Before the drivers can be utilized, the hardware configuration of the control units must conform to the relevant circuit diagram or according to the unit documentation. Furthermore, you should check the software configuration with the aid of the steps described and, if necessary, adapt it to suit your requirements. In addition to the hardware requirements

If the required driver is not installed on the computer to be utilized, the LeoPC1 installation program must be re-initiated and the required drivers installed. If only the demo version of LeoPC1 is available, contact your support team for assistance with obtaining the required drivers.

CAN Bus Interface

To set:	Click on: DevicesSettings (The "Settings to parameterize system" dialog window will onen)
Figure 4.12	Devices View System ?
Open Device Settings	Load Language F7
	Settings
	General settings tab page (changes the displayed tab page)
Figure 4.13	Settings to parameterize system 🛛 🔀
General Options	General Options Service Configuration Enable Program Modules

eral Options	
1	General Options Service Configuration Enable Program Modules
	Paths and files
	Path for alarm files: ALARMS\
	Help file for alarms:
	Data communication
	Driver: IXXAT VCI3 - CAN
	Settings
	Start communication automatically while loading the system configuration
	Remote control not activated
	Displays deactivated while parameterizing/loading language 💌
	Changes will be activated immediately by submitting OK.
	OK Cancel Apply Help
I	Select the CAN bus driver (pull down menu with all installed drivers)
	Settings (CAN Settings dialog window will open)

Figure 4.14	CAN Settings			×
CAN Settings	Boar <u>d</u> :	USB-to-CAN compact	<u></u>	<u>0</u> K
				<u>C</u> ancel
				Options
				CAN- <u>I</u> D
	<u>P</u> rotocol:	Std.	•	
	<u>C</u> hip:	CAN 1	•	
	<u>B</u> aud:	125 KB	•	
	Download <u>V</u> CI Firmware			
	Uhec <u>k</u> board	V		



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You can obtain information about the following parameters among others via: - Start...Settings... Control Panel...System and corresponding selection of the options

The documentation for the hardware being used can provide the necessary information as well.



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NOTE

If any problems occur, the driver can still be individually configured for your CAN card and adapted to vour plant.

To adapt:	Click on:	
	Options ("Options" dialog window w	ill open)
Figure 4.16	CAN Settings	X
CAN Settings - Options	Computer referring settings	
0 1	∐imeout to wait upon an answer of the slave	
	Number of repetitions to send a command	3
	System referring settings	
	CAN-ID for sending a command	831
	Offset for CAN buffer to buffer of application	1

Timeout The amount of time LeoPC1 will wait for an answer to a sent command Number of repetitions How many times a command is re-sent to the CAN bus card after a timeout.

The following entries require detailed knowledge of the device and protocol that is used.

CAN ID while sending ID to be used for sending commands Offset CAN buffer Offset of the data sent by the CAN bus to the internal buffer

NOTE

NOTE

CAN-ID.. button to change the allocation table between device no. and CAN ID no. The Select the "Allocate device No. To CAN-ID" dialog window is opened for the purpose of managing the device no. and CAN ID allocation table. This dialog window permits the user to change or delete existing entries and add new entries by marking the desired lines, changing the required inputs, and/or clicking on the corresponding button.

All connected CAN bus device numbers must be assigned here with LeoPC1. If no entry appears in this list box, communication via the CAN driver is not possible. CAN-IDs should not be assigned to more than one device. The CAN-ID for sending a command should not be assigned a device number.

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Figure 4.17	Allocate Device N	No. To CAN-ID			×
Anotate Device No. 10 CAN-ID	<u>D</u> evice-No.	CAN-ID		<u>0</u> K	
	1	801	New	<u>C</u> ancel	
			<u>S</u> et		
			<u>D</u> elete		
	, Device: 1				
	De <u>v</u> ice: 1 <u>C</u> AN-ID: 801		<u>D</u> elete		

For demonstration purposes LeoPC1 displays a driver without devices being connected. Only the time delay for saving for this demo driver can be configured. No other configurations can be achieved.

To set:	Click on:
	DevicesSettings (The "Settings to parameterize system" dialog window will open) General Options tab page (changes the displayed tab page) Select the Demo driver (pull down menu with all installed drivers) Settings (Settings - demo version dialog window will open)
Figure 4.18	Settings - Demo Version 🔀
Settings – Demo Version	Delay at saving ms DK
Editing box:	"Delay at saving"
and	Input desired time in milliseconds (ms) OK (Settings - demo version dialog window will close)

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Communication with Other Applications

CSV Interface

LeoPC1 provides for further processing of the logging data from the "Data Logging" utility of the plant, machines, or devices for use with other applications such as EXCEL or a database like ACCESS. This is the function of the CSV interface. Only the data from one device may be stored in a file that limits the interface to only being able to display the data from on device.

Components of the CSV Interface

The CSV interface consists of a normal ASCII file in CSV format. A corresponding character separates the individual entries. This allows the files to be read and processed for use in spreadsheet programs and databases with a corresponding software interface.

Procedure for the CSV Interface



NOTE

The user can adapt the system settings according to the plant requirements if required.

To prepare export:	Click on:
	SystemSystem settings (The "System settings" dialog window will open)
Figure 4.19	System ?
Open System Settings	User log off
	User Management
	System Settings
	Settings tab page (changes the displayed tab page)
Figure 4.20	System settings
System Settings	Settings Paths
	Language: English Deutsch English your system. Start data logPortuguese your system. Save data logging automatically while closing your system. in file: Settings for export data logging files Output heading line ? Seperater ;
	OK Cancel Apply Help
Desired option	Select or edit the following two parameters.
1	Output heading line? Enable by placing a check mark in the box to the left of
	the text.
	Input Separator (a semi-colon ";" is the preferred character)

 To perform export:
 Click on:

 Devices...Data logging... or click the
 D

 Devices...Data logging... or click the
 D

 Figure 4.21
 Devices

 Open Data Logging
 Load Language ...

 F7
 Standard Values ...

 Parameterize ...
 F3

F5

E a



NOTE

If no data exists, refer to "Procedure for Data Logging" on page 56 and follow the user instructions in order to log and save the required data your plant.

Data Logging ...

	<u>S</u> ave	(The "Save As" dialog window will open)	
Figure 4.22	Save As	?	×
Save Export	Save <u>i</u> n: 🔂 🖸	DL 💌 🔶 🖆 🏢 -	
	Device 1.csv		
	File <u>n</u> ame:	Device 1 Save]
	Save as <u>t</u> ype:	Excel compatible file (*.csv) Cancel	
and Editing box: or	Select from: "File name" (I Selection from EXCEL comp Click on the lected name)	blease enter the desired designation) a the directory menu and file list atible file (*.csv) Save button (the data will be exported under the se	e-



NOTE

The exported data must be in CSV format. If the file name does not end in ".csv", the data will not be able to be utilized in the spreadsheet program EXCEL or the database program ACCESS. By following the previous steps the user will ensure the data functions properly with these applications.

Chapter 5. Annex

Content of the Software Package

The software package consists of the following **file groups:**

Applications	Main.exe / Unwise.exe
Language resources	LngGer.dll (German), LngEng.dll (English), LngPrt.dll (Portuguese)
System files	System.dat (user management), Install.log/.ini (information), *.hlp/.cnt (help)
Communication drive	DrvModem.dll, DrvGW4.dll (RS-232), DrvCAN2.dll, DrvDiAc.dll (direct)
Configuration files	*.cfg (definitions), *.asm (objects), *.opt (options), *bmp (pictures)
Plant files	*.std (standard values), *.llo (loggings), *.csv (export), *.alm (alarms),
	*.dat (event recorder), *.lng (load language)



NOTE

The list below may have some missing information or information duplicated in it.

Directories and Designation of the Installed Component Files

Application	%Main directory	%				
	Main.exe		Unwise.exe		Alarms*	alm.
	Install.ini		Unwise.ini		DL*.llou	und *.csv
	MainUtil.ocx		System.dat		Lng*.lng	
	LngGer.dll		LngEng.dll		Pictures	*.bmp
	LngPrt.dll		ReadMe.txt		Std*.std	
	HelpGer.hlp		HelpGer.cnt		Tools*.a	sm und *.opt
	HelpEng.hlp		HelpEng.cnt			
	Bckgrnd.bmp		prnLogo.bmp	-		
Demo/Direct	DrvDemo.dll			DrvDiA	.c.dll	
Gateway RS-232/Modem	DrvGW4.dll			DrvMoo	dem.dll	
CAN-Bus (VCI2/VCI3)	DrvCAN2.dll		DrvCAN3.dll			
CAN components	%System% (C:\W	/INE	DOWS\SYSTEM	1 or SYS	TEM32)	
General	Cci14c26.dll	Xa	cdyapi.dll	Uci20co	ci.dll	Xatisahw.dll
	Cci14t26.dll	Drv	vrapi.dll	Cci31dj	o6.dll	Xat11reg.dll
	Cci14dp6.dll			Cci31us	sb.dll	Xat12c16.dll
	Cci14i46.dll			Cci16d	o6.dll	Xat24dp6.dll
	Tca_32.dll			Cci16c2	26.dll	Vci11unb.dll
	Pciacc32.dll			Axhost.	dll	Vci_w32.dll
	Vci_w32.dll			Xatinst.	cpl	Drivers
WinNT	Xatpcikl.sys	Cn	dy.reg		-	Xat12c1.sys
	Xatcdykl.sys	Tin	canv2.reg			Xat24dp.sys
	Mpmi2e.sys	Xat	tpcikl.reg			Xat10d25.sys
Win98 and)	Xatcdy.vxd	Mp	omi2e.vxd	Inf∖		xat20u23.sys
Win2000/XP (VCI2 only)	xat10c16.dll	xat	11dp6.dll	Xatusb.	inf	Xat10u23.sys
	xat12pc6.dll	xat	11c1.vxd	Xat_pci	.inf	Xat10d24.vxd
	xat40t16.dll	Xat	t22dp.vxd	Xat_pci	n.inf	Xat24dp.vxd
	vcil lun6.dll			Xat_isa	.inf	Xat12c1.vxd
Windows 7	SplashW.bmp	ST	S.log			
System components	Msvcp60.dll	Asy	ycfilt.dll	Comctl	32.ocx	
	Msvcrt.dll	atl.	dll	Comdlg	32.ocx	
	Msvcirt.dll	Da	o350.dll	Comcat	.dll	
	Msvbvm60.dll	mfe	c42.dll	Olepro3	2.dll	
	Msstkprp.dll	Std	ole2.tlb	Oleaut3	2.dll	

Table 5.1 Component files – Installation



The graphs and pictures (*.bmp) supplied can be altered with a standard image-editing program (CorelDraw, Microsoft[®] Paint, etc.).

The configuration files (*.cfg and *.asm) can be edited with a standard text editor (such as Microsoft[®]WordPad, Microsoft[®] NotePad, MultiEdit, etc.)

Registration Data Base

Settings in the registration database can be computer-dependent or user-dependent. The following two segments list entries that are present in the registration database. The specified values are installed as default values, which, if necessary, may be changed during the application.

Other entries may be changed, if necessary, during use of the application.

Computer-dependent [HKEY_LOCAL_MACHINE\Software\]



NOTE

The export, data logging, and system modules are comprised of code that can be configured through LeoPC1.

Application	%Main key%
Default background	"LogoBitmapFile"="Bckgrnd.bmp"
Display of splash in ms	"SplashTime"=dword:00000bb8
Aktive language	"Language"="Deutsch"
Output of export header	"ExportHeader"=dword:00000001
Active separator symbol	ExportSeperatorKey"=";"
Autostart Short-term storage	"STSAutostart"=dword:0000000
Autostart data logging	"DataLoggingAutostart"=dword:00000000
Autosaving of data logging	"DataLoggingAutosave"=dword:00000000
Active backup file	"DataLoggingAutosaveFile"=""
Time period parameter X	"DataLoggingXSetting"=dword:00000001
Start time	"DataLoggingXStart"=dword:0000000
End time	"DataLoggingXEnd"=dword:0000012c
Measured value parameter Y	"DataLoggingYSetting"=dword:00000000
Minimum value	"DataLoggingYStart"=dword:0000000
Maximum value	"DataLoggingYEnd"=dword:00000320
Sampling rate	"DataLoggingRate"=dword:00000002
Logging time period	"DataLoggingTime"=dword:0000012c
0=zero, 1=file, 2=window	"CfgSyntaxCheck"=dword:0000000
File name	"CfgSyntaxcheckFile"="syntax.log"

Table 5.2 Registration Software keys - Main



NOTE

Code comprises all installed languages, their dynamic configuration value, and the relevant assigned help file. The user can select the desired language from the "Load Language" dialog window in LeoPC1 from all available languages.

Application	%Sub key%
Languages	"Deutsch"="LngGer.dll,0"
	"English"="LngEng.dll,1"
	"Portuguese"="LngPrt.dll,2"
\Helps	"Deutsch"="HelpGer.hlp"
	"English"="HelpEng.hlp"
	"Portuguese"="HelpEng.hlp"

Table 5.3 Registration Software keys - Language and Help

1

The directory variables are comprised of code. These variables can be used in the CFG files when the bit maps or configuration files are specified. The settings can be edited through LeoPC1 under System Settings...Paths tab page.

Application	%Sub key%
\Environment	"ASM_PATH"="main directory\Tools"
	"BITMAP_PATH"="main directory\Pictures"
	"LNG_PATH"="main directory\LNG"
	"STD_PATH"="main directory\STD"
	"DL_PATH"="main directory\DL"
\DL	\Value0
	\
	\Value7

Table 5.4 Registration Software keys - Environment and DL

NOTE

The individual communication drivers are comprised of code. The driver list contains all configured interface drivers. New interface drivers are automatically entered in this list when installed. Additional plant-specific files may be found in the CFG files.

Application	%Sub key%
\Drivers	"Demo"="main directory\DrvDemo.dll"
	"Direkt"="main directory\DrvDiAc.dll "
	"Modem"=" main directory\DrvModem.dll "
	"Gateway RS-232"="main directory\DrvGW4.dll "
	"IXXAT VCI3-CAN"="main directory\DrvCAN3.dll "
\DrvDemo	"Timeout"=dword:000007d0
\DrvDiAc	"Port"=dword:00000001
\DrvGW4	"Port"=dword:00000001
\DrvModem	"Port"=dword:00000001
\DrvRS-232	"Port"=dword:00000001
\DrvCAN	Entries are dependent on the driver version and the hard-
	ware that is installed.

Table 5.5 Registration Software keys - Drivers

NOTE

Further entries are achieved under [HKEY_CLASSES_ROOT], [HKEY_USERS\Software\], and [HKEY_USERS\.DEFAULT\Software\]. These are used for internal application functions. If necessary, they can refer to other codes.

FAQ

Listing of Selected Error Messages

Error number	Description
-1	Unknown error
-13	COM-Port is not connected/available
-15	Error while modem initialization
-16	Error while connecting (modem)
-123	Wrong device/communication-ID
-232	Access to device was refused:
	wrong module was selected, Password is missing/wrong, etc.
-1009	VCI (CAN) was canceled
-1011	VCI (CAN) was disconnected
-1012	CAN bus buffer overflow
-1013	CAN bus did not answer

Table 5.6 FAQ - Error descriptions

No faults are logged in an Error File.

If new files are not created, the user can check this by adding a manual entry. If this is not possible, check whether the directory exists that is entered in the device settings actually.

The Data for Data Logging is stored in the Swap File and not in a Normal File.

Please check whether there is a subfolder named DL in your folder containing the configuration file. If not, create this folder, as the data logging files are stored here. If this folder does not exist, the data logging files will be stored in the swap file.

The PC has crashed. Is my Logging Data now lost?

A special logging procedure ensures that the data is not lost, even if the computer crashes. Start up the PC and restart LeoPC1. The data will be available until data logging is restarted.

Driver Settings are reset again and again.

Ensure that the CFG file is not write-protected. If the CFG file is write protected, disable the write protection since some of the settings are managed in the CFG.

Why is the Logo of the LeoPC1 not printed out?

Check if the CFG file was loaded from the mains directory. If it was opened from another directory, then the suited logo file ("prnLogo.bmp") must be stored there. The file is in bmp format and has the following size: width: 308 pixel, height: 86 pixel.

Starting the Configuration the Message appears: "File not found *.opt"

The required *.opt file is expected to be located in the sub directory "Tools". It must be in the same directory as the cfg file, which has to be opened. For example the *.cfg file is located in:

" C:\Program Files\Woodward\LeoPC1\cfg ", then the *.opt file is expected to be located in:

" C:\Program Files\Woodward\LeoPC1\Tools ".

Is Communication possible via COM Interface (direct, Gateway RS-232), if the Laptop/PC doesn't have a (free) COM Port?

It is possible to configure a COM port over a USB interface with compatible hardware and software that can be utilized by LeoPC1.

You cannot configure!

Problem 1: Neither reading nor writing is possible

Problem A:	Error sources on the devices side:
Question 1	Is the parameter "Direct para" in the device
	configured "ON" for direct drivers
or	"OFF" for all other communication drivers?
	(Modem, Gateway RS-232, and IXXAT VCI3 – CAN)?
Question 2	Are the connections for the PC, direct parameterization (DPC) cable, and the
	device good?
	If necessary test with a different DPC cable!
Question 3	Is an extension cable being used?
	Check the polarity to ensure the input pins are connected to the correct out-
	put pins.
Darahlara Da	
Problem B:	Error sources on the software side:
0 1	
Question 1	Have you selected the correct driver for your configuration?
Question 1	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver.
Question 1 Question 2	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings?
Question 1 Question 2	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port
Question 1 Question 2	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings.
Question 1 Question 2 Question 3	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings. Is any other software using the COM port?
Question 1 Question 2 Question 3	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings. Is any other software using the COM port? Close the software application that is using the COM port so LeoPC1 may
Question 1 Question 2 Question 3	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings. Is any other software using the COM port? Close the software application that is using the COM port so LeoPC1 may start communications. The COM port can only be utilized by one application
Question 1 Question 2 Question 3	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings. Is any other software using the COM port? Close the software application that is using the COM port so LeoPC1 may start communications. The COM port can only be utilized by one application at a time.
Question 1 Question 2 Question 3	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings. Is any other software using the COM port? Close the software application that is using the COM port so LeoPC1 may start communications. The COM port can only be utilized by one application at a time. Are the communication timeouts configured correctly?
Question 1 Question 2 Question 3 Question 4	Have you selected the correct driver for your configuration? If it's INCORRECT, select the correct driver. Is the correct COM port configured in the driver settings? Ensure the correct COM port being utilized is the same as the COM port configured in the driver settings. Is any other software using the COM port? Close the software application that is using the COM port so LeoPC1 may start communications. The COM port can only be utilized by one application at a time. Are the communication timeouts configured correctly? Use the guide values in the driver settings (it is better to set higher values if



NOTE

Modem connections from LeoPC1 must comply with the operating instructions for the modem being utilized. Other AT commands may result from this pre-specified as defaults.

Problem 2: Reading is possible, but writing not.

Problem B:	Error sources on the software side:	
Question 5	Has the correct password been input via LeoPC1?	
	If not, input the level 2 code in the device.	
Question 6	Are the expected password and the input data correct?	
	If not, input the correct password and/or data.	

Problem 3: Reading and writing of individual parameter values possible via input, but parameters are not being read when "Read All" is used.

Problem B: Error sources on the software side:

Question 7 Are the formatted values readable? If not, the problem most likely is with the device.



NOTE

It is recommended to establish communication with a control device via the "Parameterization" dialog window to perform readout of the parameters and storage of the STD file rather than producing an STD file offline that will be loaded into a control unit at a later date.

How to Contact Woodward

Please contact following address if you have questions or if you want to send a product for repair:

Woodward GmbH Handwerkstrasse 29 70565 Stuttgart - Germany

Phone:	+49 (0) 711 789 54-510	(8.00 - 16.30 German time)
Fax:	+49 (0) 711 789 54-101	
E-mail:	stgt-info@woodward.com	

For assistance outside Germany, call one of the following international Woodward facilities to obtain the address and phone number of the facility nearest your location where you will be able to get information and service. Please contact the Woodward Customer Service Department or consult our worldwide directory on Woodward's website (**www.woodward.com**) for the name of your nearest Woodward distributor or service facility. [For worldwide directory information, go to **www.woodward.com/locations**.]

Internet Download of the Software

The latest version of the LeoPC1 you can download from the following internet page **www.woodward.com/software/Software.cfm** and select LeoPC1 from the list right there.

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